



SMART DOOR SOLUTIONS



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Assembly Instructions

Door drive for lifts

TSG V4

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1.20.91000

V4.21

15.01.2026

## Imprint

|              |  |
|--------------|--|
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# Contents

|       |   |    |
|-------|---|----|
| 1     | About this manual.....  | 6  |
| 1.1   | Purpose.....  | 6  |
| 1.2   | Scope.....  | 6  |
| 1.3   | Version information .....   | 6  |
| 1.4   | Contact information .....   | 6  |
| 1.5   | Target group.....   | 6  |
| 1.6   | Means of representation .....                                     | 6  |
| 1.7   | Device information .....  | 7  |
| 1.8   | Other applicable documents .....                                  | 7  |
| 2     | Safety .....  | 8  |
| 2.1   | General safety instructions.....                                  | 8  |
| 2.2   | Intended use .....  | 8  |
| 2.3   | Responsibility of the owner .....                                 | 8  |
| 2.3.1 | Obligations of the owner .....                                    | 8  |
| 2.3.2 | Owner obligations to the personnel .....                          | 8  |
| 2.4   | Personnel requirements .....                                      | 9  |
| 2.4.1 | Personnel qualification and scope of work.....                    | 9  |
| 2.4.2 | Personal protective equipment .....                               | 9  |
| 2.5   | Product-specific hazards.....                                     | 10 |
| 2.5.1 | Mechanical hazards .....  | 10 |
| 2.5.2 | Heat hazards.....   | 10 |
| 2.5.3 | Electrical hazards.....   | 10 |
| 2.5.4 | Hazards due to improper use.....                                  | 11 |
| 2.6   | Warnings .....  | 11 |
| 2.6.1 | Structure of warning notices .....                                | 11 |
| 2.6.2 | Meaning of the signal words and symbols .....                     | 11 |
| 2.7   | Illegible signage .....   | 12 |
| 3     | Product description.....  | 13 |
| 3.1   | Overview .....  | 13 |
| 3.2   | Components.....   | 13 |
| 3.3   | Motor position.....   | 14 |
| 3.4   | Housing designs.....  | 14 |
| 3.4.1 | TSG V4 external electronic components .....                       | 14 |
| 3.5   | Dimensions .....  | 17 |
| 3.6   | TSG V4 electronic components .....                                | 18 |
| 3.6.1 | Interfaces and displays of the TSG V4 electronic components ..... | 18 |
| 3.6.2 | Technical data of the TSG V4 electronic components .....          | 19 |
| 3.6.3 | Mains connection .....  | 22 |
| 3.6.4 | Internal fusing .....   | 23 |
| 3.6.5 | Inputs and outputs .....  | 24 |
| 3.6.6 | Motor connection .....  | 30 |
| 3.6.7 | External control voltage .....                                    | 31 |

|       |  |    |
|-------|--|----|
| 3.7   | TSG options .....  | 32 |
| 3.7.1 | TSG web interface .....                                    | 32 |
| 3.7.2 | Emergency power supply.....                                | 32 |
| 3.7.3 | Light curtain .....  | 32 |
| 4     | Transportation and storage .....                           | 34 |
| 4.1   | Transportation .....                                       | 34 |
| 4.2   | Packaging .....  | 34 |
| 4.3   | Storage.....   | 34 |
| 5     | Mechanical mounting .....                                  | 35 |
| 5.1   | Requirements.....  | 35 |
| 5.2   | Procedure.....   | 35 |
| 5.2.1 | Assembly .....   | 35 |
| 5.2.2 | Mounting on the door .....                                 | 37 |
| 5.3   | Deflection pulley.....                                     | 37 |
| 5.4   | Timing belt.....   | 38 |
| 6     | Electric setting, parameterisation and commissioning ..... | 39 |
| 6.1   | Overview .....   | 39 |
| 6.2   | 7-segment display .....                                    | 39 |
| 6.3   | Menu structure .....                                       | 41 |
| 6.4   | Manual measuring.....                                      | 41 |
| 6.5   | Manual mode/manual travel.....                             | 43 |
| 6.6   | Standard parameters .....                                  | 43 |
| 6.6.1 | Basic setting.....   | 43 |
| 6.6.2 | Travel profiles with default parameters .....              | 43 |
| 6.6.3 | User setting of the P parameters .....                     | 44 |
| 6.7   | Extended parameters.....                                   | 45 |
| 6.7.1 | Travel profiles with extended parameters .....             | 45 |
| 6.7.2 | User setting of the c parameters.....                      | 46 |
| 6.7.3 | Using setting of the b parameters .....                    | 47 |
| 6.7.4 | User setting of the h parameter .....                      | 48 |
| 6.7.5 | Mode setting with parameter hA .....                       | 50 |
| 6.7.6 | Error codes (E parameters) .....                           | 52 |
| 6.7.7 | Operating state (r parameters).....                        | 53 |
| 6.7.8 | User setting of the Au parameters .....                    | 54 |
| 6.8   | Setting the force limitation.....                          | 55 |
| 6.8.1 | Basic principles .....                                     | 55 |
| 6.8.2 | Maximum kinetic energy .....                               | 55 |
| 6.8.3 | Maximum static force .....                                 | 55 |
| 6.8.4 | Obstacle detection in closing direction.....               | 56 |
| 6.8.5 | Obstacle detection in opening direction .....              | 56 |

|       |  |    |
|-------|--|----|
| 6.9   | Special functions .....  | 57 |
| 6.9.1 | Holding torque in the end positions.....   | 57 |
| 6.9.2 | Braking function in case of fast manual movement .....                             | 57 |
| 6.9.3 | Closing the door on deactivation or failure of the external protective device..... | 57 |
| 6.9.4 | Stop function .....  | 58 |
| 6.9.5 | Leading limit switch.....  | 59 |
| 6.9.6 | Mechanical transmission.....   | 60 |
| 7     | Operation.....   | 61 |
| 7.1   | Restart after power failure and restored mains .....                               | 61 |
| 7.2   | Normal operation.....  | 61 |
| 8     | Maintenance.....   | 62 |
| 8.1   | Maintenance safety instructions .....  | 62 |
| 8.2   | Regular checks .....   | 63 |
| 9     | Troubleshooting.....   | 64 |
| 9.1   | Troubleshooting safety instructions.....   | 64 |
| 9.2   | Error with displayed error code .....  | 65 |
| 9.3   | Error without displayed error code .....   | 68 |
| 10    | Dismantling and disposal .....   | 69 |
| 10.1  | Dismantling and disposal safety instructions .....                                 | 69 |
| 10.2  | Disposal .....   | 70 |
| 11    | Declaration of incorporation .....   | 71 |

# 1 About this manual

## 1.1 Purpose

This mounting manual contains important information on the mounting, commissioning, function and maintenance of the device. Observing the manual helps to avoid hazards, repair costs and downtimes and increases the reliability and life of the device.

## 1.2 Scope

This mounting manual applies to the following device: door operator TSG V4.

## 1.3 Version information

The issue status of this mounting manual is stated on the cover page and in the footers on every page.

Always keep and use the current version of all documentation.

If an outdated version of this or the required supplementary documentation is used, this can lead to faulty mounting, commissioning or operation.

## 1.4 Contact information

See page 2.

## 1.5 Target group

This mounting manual is directed at end customers of Langer & Laumann Ing.-Büro GmbH.

In addition to reading this mounting manual, the following requirements and previous technical knowledge of the user is required for correct operation of the device:

- comprehensive technical knowledge of the existing facilities
- knowledge of the operating manuals of these facilities
- Classification as skilled personal

## 1.6 Means of representation

The following presentation formats are used in this mounting manual:

**Parameter** Bold and italic print, example: ***P8***.

**Parameter values** Typewriter font, example: 05.

**Displays** The content of the 7-segment display is presented as shown in the following examples: "nL", "RR", "o5".

**Instructions** Requirements for an instruction are represented with a tick.

The steps to be carried out are numbered.

Results of the individual steps are marked by a black arrow. The overall result of an instruction is highlighted by a white arrow in a black circle.

### Example

- ✓ Requirement
- 1. Instruction (Step 1)
- 2. Instruction (Step 2)
  - ⇒ The interim result or system response to step 2
- 3. Instruction (Step 3)

⌚ Overall result of the instruction

**Lists** Lists without a compulsory order are shown as a list with bullet points (en dash).

### Example

- Property A
  - Detail 1
  - Detail 2
- Property B
  - Detail 1
  - Detail 2

## 1.7 Device information

The most important device information is provided on the nameplate.

## 1.8 Other applicable documents

The following documents are required for work that is not described in this mounting manual:

- Information about components not manufactured and supplied by Langer & Laumann
- Overall operating manual of the facility

## 2 Safety

### 2.1 General safety instructions

The door drive may not be mounted, commissioned or maintained without the information in this mounting manual. Before starting any work, the personnel must have read through this mounting manual carefully and understood it.

The safety instructions and other instructions in this mounting manual and the safety instructions and danger warnings attached to the door drive must be observed.

The local accident prevention regulations and general safety provisions that apply at the place of use must be observed.

### 2.2 Intended use

The TSG V4 door operator is a door drive for automatic operation of horizontally or vertically moved sliding doors (vertical lift doors).

### 2.3 Responsibility of the owner

#### 2.3.1 Obligations of the owner

The owner is responsible for ensuring that the facility is set up, installed, operated and maintained properly.

The owner must ensure safe operation and observe the requirements listed in the operating manual.

The owner is responsible for ensuring that the safety instructions listed in the [► Product-specific hazards \[p. 10\]](#) section, the local accident prevention regulations and the local environmental protection provisions are complied with at all times.

#### 2.3.2 Owner obligations to the personnel

- The owner ensures that only appropriately instructed and authorised personnel work on the facility.
- Unauthorised persons must be kept away from the facility.
- The personnel has the necessary qualification and receives the necessary training.
- The owner ensures that no one whose ability to respond is impaired, for example, by drugs, alcohol, medication or similar works on the facility.
- The owner ensures that the operating, maintenance and servicing personnel have been thoroughly familiarised with all safety instructions and that the safety instructions are followed.
- The personnel can examine the Assembly instructions at any time. The Assembly instructions must be kept near the facility.
- The owner makes sure that the personnel receive and wear the specified personal protective equipment.

## 2.4 Personnel requirements

### 2.4.1 Personnel qualification and scope of work

The work described in these instructions places different demands on the qualifications of personnel. Insufficiently qualified personnel cannot correctly assess the potential risks and may expose themselves and others to the risk of injury. Insufficiently qualified personnel are not permitted to enter work areas/danger zones. Persons whose reactions are influenced, e.g. by drugs, alcohol or medication, must not work on the system.

**Qualified personnel** Only qualified personnel (lift fitters for specific activities in lift construction in accordance with DGUV 303-001) may work on mechanical components.

**Qualified electricians** Only qualified electricians or lift fitters with advanced training as qualified electricians for specific activities in lift construction may work on electrical components in accordance with DGUV 303-001.

### 2.4.2 Personal protective equipment

Personal protective equipment is used to protect people against health and safety impairments during their work. The specified protective equipment must be worn.

| Symbol  | Meaning  |
|---|--|
|   | Wearing protective work clothing protects against hazards in the workplace.                  |
|  | Wearing slip-resistant safety footwear protects against injuries to the feet.                |
|  | Wearing cut and puncture-resistant protective gloves protects against injuries to the hands. |
|  | Wearing a protective cap protects against head injuries.                                     |
|  | Wearing goggles protects against eye injuries.   |
|  | Wearing hearing protection protects against hearing damage.                                  |
|  | Wearing a fall arrest system protects against falls.   |

Table 1: Personal protective equipment

## 2.5 Product-specific hazards

### 2.5.1 Mechanical hazards

Moving parts can entangle and crush or bruise parts of the body.

Parts with sharp edges and pointed corners pose a risk of injury.

- Never touch moving parts.
- Keep the movement area of moving parts clear.
- Before any work on components or individual parts, switch off the TSG V4 and secure it against reconnection.
- Only carry out work on components if they are at a complete standstill.
- After completing the work on components, reattach all covers, threaded fasteners and safety devices immediately.
- Do not bypass, dismantle or manipulate protective devices.
- Wear the specified personal protective equipment.
- Set the parameters according to the relevant standards.

### 2.5.2 Heat hazards

The motor of the TSG V4 can become hot in continuous operation, thus causing a risk of burns.

- Allow the motor to cool before starting the work.
- Wear the specified personal protective equipment (suitable protective gloves).

### 2.5.3 Electrical hazards

Touching live parts inside the TSG V4 or in the area of the electrical equipment poses a risk to life.

- Work on the electrical installation may only be carried out by trained electrically skilled personnel.
- Fuse the TSG V4 as shown on the circuit diagram.
- Only use original fuses.
- Always carry out the 5 electrical safety steps:
  - Disconnect completely
  - Secure against reconnection
  - Verify that the installation is dead
  - Carry out earthing and short-circuiting
  - Provide protection against adjacent live parts

## 2.5.4 Hazards due to improper use

The TSG V4 must only be used as intended. This means observing all instructions in this Assembly instructions in every stage of the life cycle.

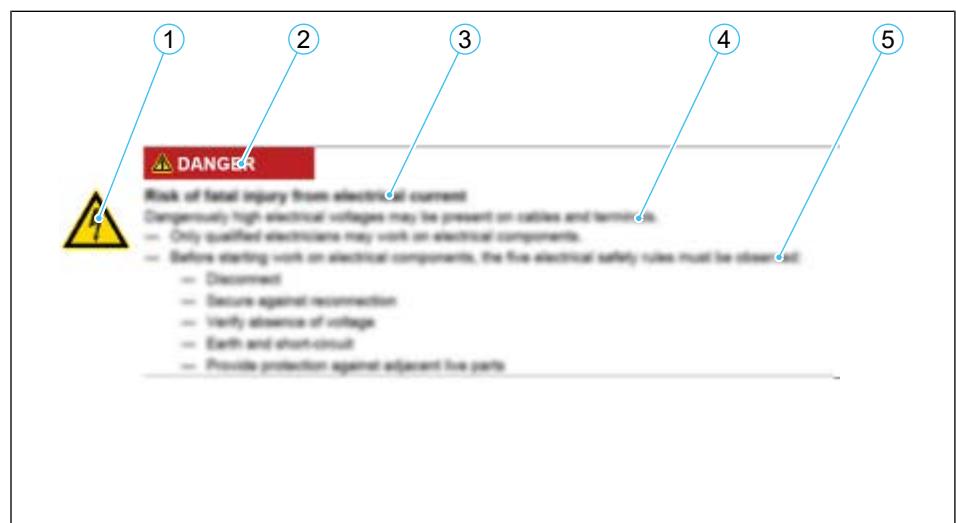
Misuses are, for example:

- Carrying out work without adequate qualification/technical knowledge and without instruction
- Structural changes not planned by the manufacturer
- Use of unapproved additional equipment
- Bypassing/removing protective devices
- Commissioning a damaged or non-functional device

## 2.6 Warnings

### 2.6.1 Structure of warning notices

All warning notices in this document are structured as follows:



|   |                                 |   |   |
|---|---------------------------------|---|---|
| 1 | Hazard symbol                   | 2 | Signal word                             |
| 3 | Type and source of hazard       | 4 | Possible consequences of non-observance |
| 5 | Procedure for hazard prevention |   |   |

### 2.6.2 Meaning of the signal words and symbols

The following signal words are used in this document:

| Signal word | Meaning, consequences if not prevented   |
|-------------|--|
| DANGER      | Warns of an imminent hazardous situation which results in death or serious injury.           |
| WARNING     | Warns of a potential hazardous situation, which could result in death or serious injury.     |
| CAUTION     | Warns of a potential hazardous situation, which could result in minor or moderate injury.    |
| ATTENTION   | Warns of a hazardous situation, which can result in material damage or environmental damage. |

Table 2: Meaning of the signal words

The following hazard-specific symbols are used in this document:

| Symbol   | Designation        |
|--|--------------------|
|   | Automatic start-up |
|   | Electrical hazard  |
|   | Gear wheels        |
|   | General warning    |
|  | Hot surface        |

Table 3: Meaning of the hazard-specific symbols

## 2.7 Illegible signage

During the course of time, labels and signs can become dirty or unrecognisable/illegal in some other way so that dangers are not recognised and necessary operating instructions cannot be followed. To avoid injuries, all warnings must be kept in a good, legible condition at all times. Damaged signs or labels must be renewed immediately.

## 3 Product description

### 3.1 Overview

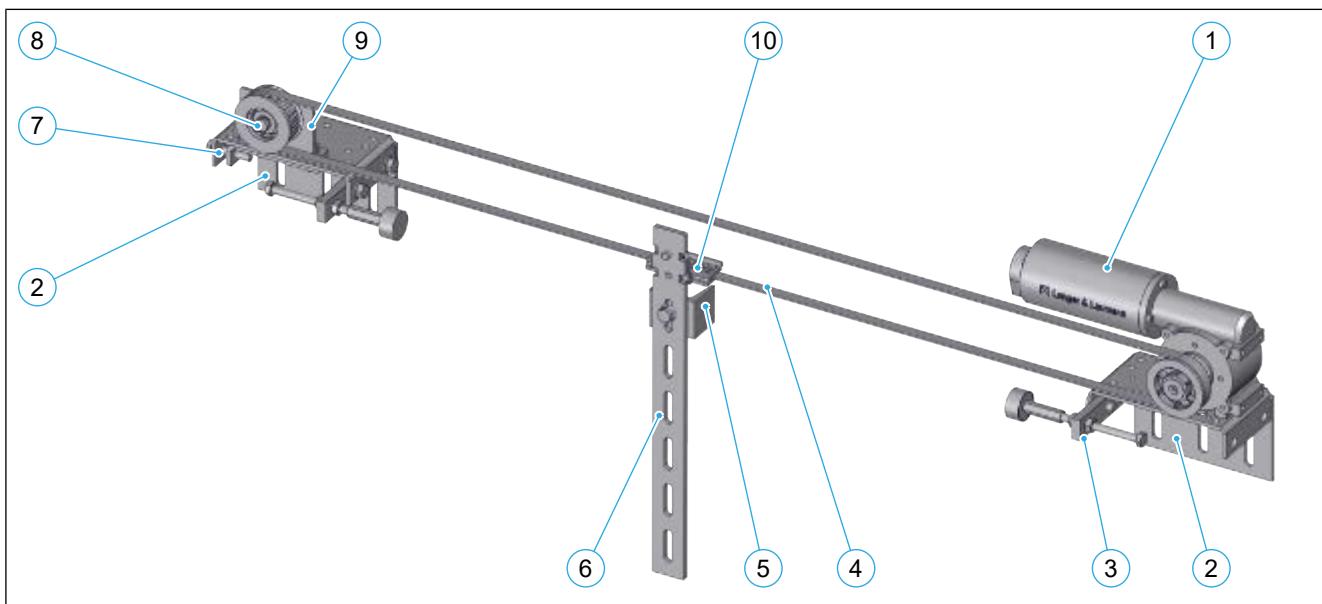
The TSG V4 door operator is a door drive for automatic operation of horizontally or vertically moved sliding doors (vertical lift doors). Langer & Laumann does not accept any liability for applications outside the defined application. The speeds and accelerations can be adjusted. The door opening is determined by a measurement process.

When operated as a power operated guard, the door operator TSG V4 meets the requirements of EN 81-20 with category 2.

The TSG V4 can be used for up to approx. 20,000 mm travel distance. The door panel weights in the standard configuration must not exceed 400 kg. Speed increases or reductions at the timing belt change the kinetic and static forces, see ▶ [Mechanical transmission \[p. 60\]](#).

### 3.2 Components

The following figure shows the assembled mechanical components of the device by way of example.



III. 1: Example TSG assembly

| Item | Part number   | Designation                        |
|------|---------------|------------------------------------|
| 1    | 8.20.40000.X1 | TSG drive (here: left version)     |
| 2    | 1.20.60040    | TSG combined bracket, standard     |
| 3    | 1.20.60030    | TSG stop set (incl. buffer)        |
| 4    | 1.20.xxxx     | Timing belt                        |
| 5    | 1.20.60020    | TSG stop on the door panel coupler |
| 6    | 1.20.60004    | TSG door panel coupler             |
| 7    | 1.20.60110    | TSG mounting link                  |
| 8    | 1.20.60003    | TSG deflection pulley              |
| 9    | 1.20.60013    | TSG bracket for deflection pulley  |
| 10   | 1.20.60005    | TSG timing belt lock               |

### 3.3 Motor position

The TSG drive is available with two different motor positions. The motor position is independent of the opening direction or the opening method of the door to be moved. The TSG drive with output left can, for example, be installed on the right or left-hand side.

|   |   |
|---|---|
| <b>Motor output position left</b><br>When looking at the gear head with the foot mounting at the bottom, the output is on the left-hand side.   |  |
| <b>Motor output position right</b><br>When looking at the gear head with the foot mounting at the bottom, the output is on the right-hand side. |  |

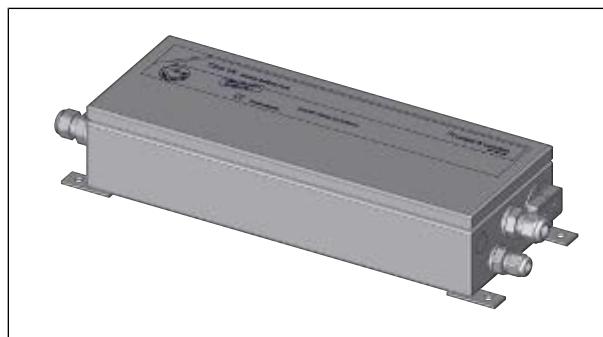
### 3.4 Housing designs

The TSG V4 electronic components are available in the following housing designs:

- TSG V4-external electronic components

#### 3.4.1 TSG V4 external electronic components

This housing design is splash-proof and is fixed in a suitable position near the TSG drive with four screws.



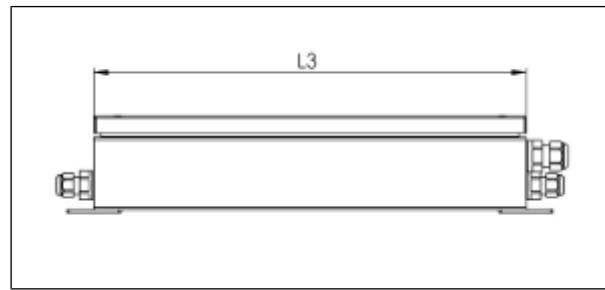
III. 2: Front view of the TSG V4 external electronic components

**Cable entry** The cables can be optionally fed in through the left or right side with cable glands through prepunched holes in the housing. The motor and encoder cables use a common dividable cable gland.

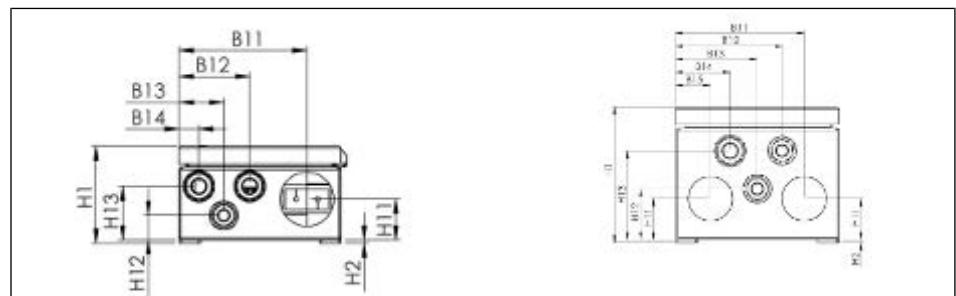
#### ATTENTION

##### Possible damage

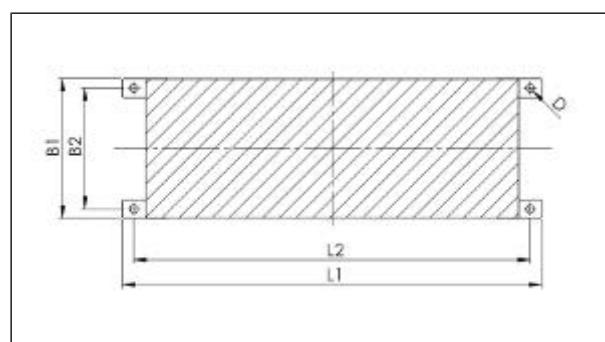
- On opening the prepunched hole, make sure that the TSG V4 electronic components are not damaged and no metal parts get on them.
- Close off all broken out openings using the threaded fasteners provided in order to main the degree of protection.

**Dimensioned and assembly drawings**

III. 3: Long side view with dimensions of the TSG V4 external electronic components



III. 4: Narrow side view with dimensions of the TSG V4 external electronic components (in two different available heights)



III. 5: Plan view with dimensions of the TSG V4 external electronic components

**Dimensions and weight**

| Property                            | Abbreviation | Value at H1 = 88 mm                                     | Value at H1 = 125 mm |
|-------------------------------------|--------------|---|----------------------|
| Housing length                      | L3           | 400 mm  |                      |
| Total length                        | L1           | 425 mm  |                      |
| Total width                         | B1           | 150 mm  |                      |
| Distance between mounting holes     | B2           | 130 mm  |                      |
| Mounting hole diameter              | D            | 8.5 mm  |                      |
| Total height                        | H1           | 88 mm   | 125 mm               |
| Height of fastening lugs            | H2           | 3 mm  | 3 mm                 |
| Height of hole, cable gland 1       | H11          | 36 mm   | 38 mm                |
| Height of hole, cable gland 2       | H12          | 21 mm   | 47 mm                |
| Height of hole, cable gland 3 and 4 | H13          | 48 mm   | 82 mm                |
| Hole distance, cable gland 1        | B11          | 121 mm  | 118 mm               |
| Hole distance, cable gland 2        | B12          | 68 mm   | 98 mm                |
| Hole distance, cable gland 3        | B13          | 44 mm   | 75 mm                |
| Hole distance, cable gland 4        | B14          | 21 mm   | 50 mm                |
| Hole distance, cable gland 5        | B15          |   | 32 mm                |
| Weight                              |              | approx. 4.1 kg...5.8 kg<br>(depending on the equipment) |                      |

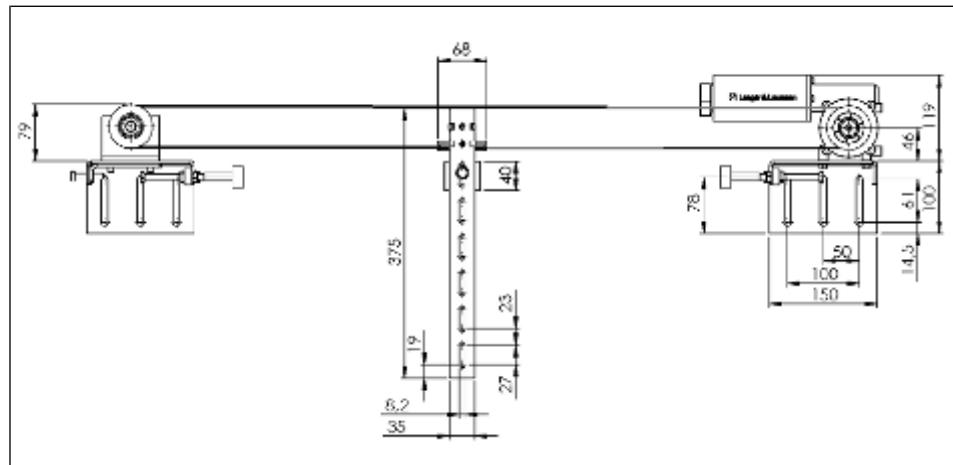
Table 4: Dimensions and weight of the TSG V4 external electronic components

| Cable gland | Cable diameter |
|-------------|----------------|
| M16         | 5 mm...10 mm   |
| M20         | 8 mm...13 mm   |

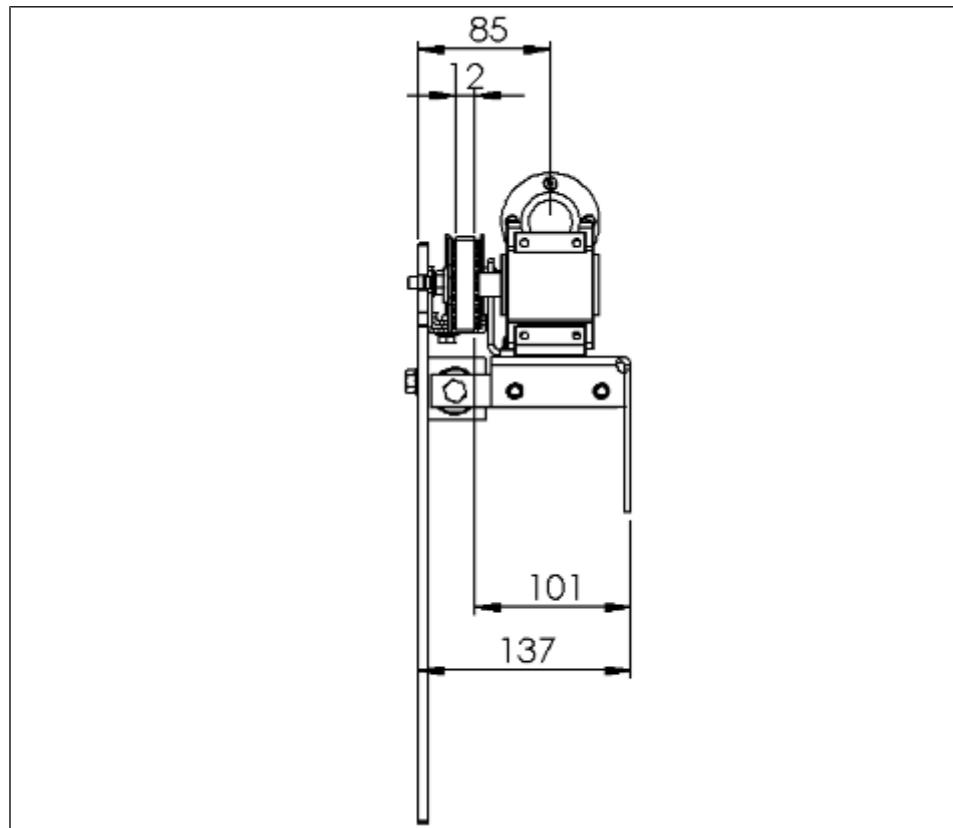
Table 5: Cable diameters and cable glands of the TSG V4 external electronic components

### 3.5 Dimensions

The following figures show the most important dimensions of the mechanical part of the door drive.



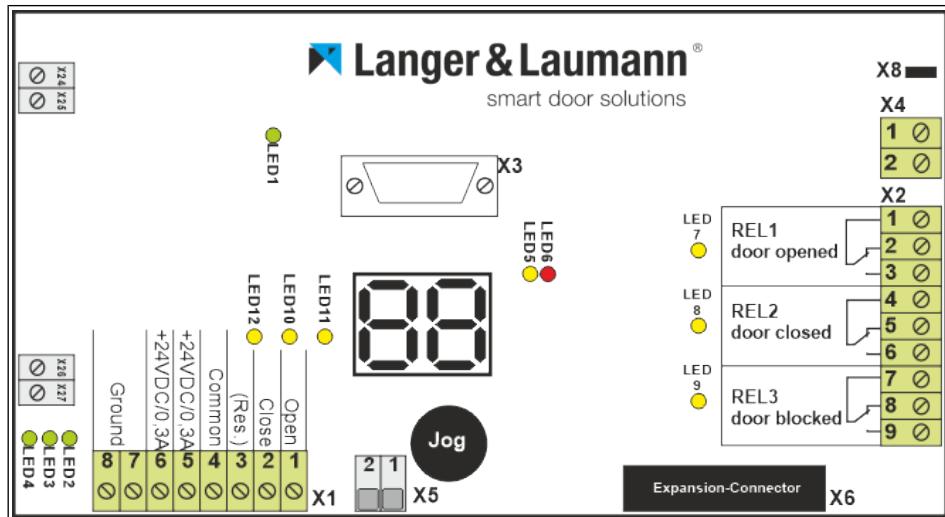
III. 6: Dimensioning of the door drive's mechanics (front view) (all dimensions in mm)



III. 7: Dimensioning of the door drive's mechanics (side view) (all dimensions in mm)

## 3.6 TSG V4 electronic components

### 3.6.1 Interfaces and displays of the TSG V4 electronic components



III. 8: Position of the interfaces and displays of the TSG V4 electronic components

| Designation | Meaning  |
|-------------|--|
| X1          | Inputs   |
| X2          | Outputs  |
| X3          | Motor encoder  |
| X4          | Motor  |
| X5          | Stop input (see also <a href="#">Connection for the stop function (X5) [p. 29]</a> ) |
| X6          | Expansion connector  |
| X8          | Motor shield   |
| X24/25      | Internal power supply  |
| X26/27      | Internal power supply  |

Table 6: Interfaces of the TSG V4 electronic components

| Designation | Meaning   |
|-------------|---|
| LED 1       | Operating voltage 38 VDC  |
| LED 2       | Operating voltage 5 VDC   |
| LED 3       | Operating voltage 12 VDC  |
| LED 4       | Operating voltage 24 VDC  |
| LED 5       | Check. The uniform flashing of the LED indicates that the processor is working. If the LED has gone out or if it is lit continuously, a defect exists.  |
| LED 6       | Overload. The LED indicates that an unusually high motor current is flowing. This occurs while checking the end positions or just before a blockage, for example, due to a sluggish door. If the door weight is set too low, if the blockage detection is set too low, the LED reacts more sensitively. |
| LED 7       | "Door is open" output signal  |
| LED 8       | "Door is closed" output signal  |
| LED 9       | "Door is blocked" output signal   |

| Designation | Meaning                   |
|-------------|---------------------------|
| LED 10      | “Close door” input signal |
| LED 11      | “Open door” input signal  |
| LED 12      | Input signal (reserve)    |

Table 7: Displays of the TSG V4 electronic components

### 3.6.2 Technical data of the TSG V4 electronic components

| Property  | Value                       |
|---|-----------------------------|
| <b>Connection voltage (input characteristics)</b> |                             |
| 115 V version                                     |                             |
| Connection voltage                                | 115 VAC ±15 % (L, N, GRD)   |
| Power consumption                                 | 1.8 A                       |
| Number of phases                                  | 1 (AC)                      |
| Frequency   | 50/60 Hz                    |
| Short-circuit current                             | 4.0 A<br>(internal fusing)  |
| 200 V version                                     |                             |
| Connection voltage                                | 200 VAC ±15 % (L, N, GRD)   |
| Power consumption                                 | 1.1 A                       |
| Number of phases                                  | 1 (AC)                      |
| Frequency   | 50/60 Hz                    |
| Short-circuit current                             | 2.0 A<br>(internal fusing)  |
| 230 V version                                     |                             |
| Connection voltage                                | 230 VAC ±15 % (L, N, GRD)   |
| Power consumption                                 | 0.9 A                       |
| Number of phases                                  | 1 (AC)                      |
| Frequency   | 50/60 Hz                    |
| Short-circuit current                             | 1.25 A<br>(internal fusing) |
| 400 V version                                     |                             |
| Connection voltage                                | 400 VAC ±10 % (L1, L2, GRD) |
| Power consumption                                 | 0.5 A                       |
| Number of phases                                  | 2 (AC)                      |
| Frequency   | 50/60 Hz                    |
| Short-circuit current                             | 1.25 A<br>(internal fusing) |
| 480 V version                                     |                             |
| Connection voltage                                | 480 VAC ±10 % (L1, L2, GRD) |
| Power consumption                                 | 0.4 A                       |
| Number of phases                                  | 2 (AC)                      |
| Frequency   | 50/60 Hz                    |
| Short-circuit current                             | 1.25 A<br>(internal fusing) |

| Property   | Value   |
|--|---|
| <b>Motor connection (X4, output characteristics)</b>   |   |
| Voltage range  | 0 VDC...38 VDC  |
| Current  | 2.5 A   |
| Peak current   | 12 A  |
| Number of phases   | 2   |
| Frequency  | 16 kHz  |
| <b>Fusing on site</b>  |   |
| 115 V version  | 10 A, tripping characteristic B or C  |
| 200 V version  | 10 A, tripping characteristic B or C  |
| 230 V version  | 10 A, tripping characteristic B or C  |
| 400 V version  | 5 A per phase, tripping characteristic B or C   |
| 480 V version  | 5 A per phase, tripping characteristic B or C   |
| <b>Power consumption at rest</b> , without applied input signal, not in the end position         | approx. 3 W   |
| <b>Maximum power consumption</b>   |   |
| 115 V version  | 1.8 A   |
| 200 V version  | 1.1 A   |
| 230 V version  | 0.9 A   |
| 400 V version  | 0.5 A   |
| 480 V version  | 0.4 A   |
| Depending on the door weight and parameter setting, short-term (< 1 s) higher currents can flow. |   |
| <b>Maximum length of the cable to the motor or encoder</b>                                       | 20 m  |
| <b>Allowable storage/transport temperature</b>   | -20 °C...+60 °C   |
| <b>Maximum change</b>  | 20 K/h  |
| <b>Allowable average ambient operating temperature</b> (for nominal data, no direct sunshine)    | -20 °C...+60 °C   |
| <b>Installation altitude</b>   | Up to 1000 m above sea level without limitation<br>1000 m to 2000 m above seal level with reduced performance |
| <b>Degree of protection</b>  |   |
| TSG V4-external electronic components  | IP54  |
| <b>Ambient requirements</b>  |   |
| Overvoltage category   | III   |
| Pollution degree   | 2   |
| Relative humidity  | 10 %...90 %, noncondensing  |

Table 8: Technical data of the TSG V4 electronic components

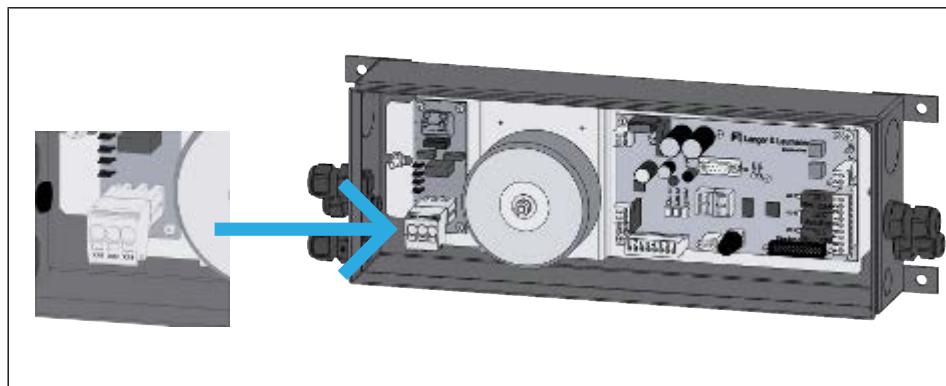
The TSG V4 electronic components are suitable for use in an electric circuit that can supply no more than 5000 A<sub>RMS</sub> at maximum 480 V, if this is protected by a circuit-breaker with an interrupting rating of not less than 10,000 A<sub>RMS</sub> at maximum 480 V.

**For use in the USA:** integrated semi-conductor short-circuit protection does not provide any protection for branch cables. The branch circuit must be protected in compliance with the manufacturer's instructions, the National Electrical Code and additional local regulations.

**For use in Canada:** integrated semi-conductor short-circuit protection does not provide any protection for branch cables. The branch circuit must be protected in compliance with the Canadian Electrical Code, Part I.

### 3.6.3 Mains connection

The TSG V4 is available for different mains connection voltages. The mains voltage connectable at the device is stated on the nameplate. The following figure shows the position of the mains connection terminals.



III. 9: Mains power connection of the TSG V4 external electronic components

#### **DANGER**

##### **Danger of death from electric shock**



Dangerously high electric voltages are applied to terminals X18 and X19 inside the device.

- Work on electrical components may only be carried out by electrically skilled personnel.
- Before starting any work on the electrical components, complete the five electrical safety steps:
  - Disconnect completely
  - Secure against reconnection
  - Verify that the installation is dead
  - Carry out earthing and short-circuiting
  - Provide protection against adjacent live parts

| Pin           | Assignment |                                 |
|---------------|------------|---------------------------------|
| 115 V version |            |                                 |
| X18           | L          | 115 VAC $\pm 15\%$<br>50/60 Hz  |
| X19           | N          |                                 |
| X20-GRD       | GRD        | Protective conductor connection |
| 200 V version |            |                                 |
| X18           | L          | 200 VAC $\pm 15\%$<br>50/60 Hz  |
| X19           | N          |                                 |
| X20-GRD       | GRD        | Protective conductor connection |
| 230 V version |            |                                 |
| X18           | L          | 230 VAC $\pm 15\%$<br>50/60 Hz  |
| X19           | N          |                                 |
| X20-GRD       | GRD        | Protective conductor connection |
| 400 V version |            |                                 |

| Pin           | Assignment |                                 |
|---------------|------------|---------------------------------|
| X18           | L1         | 400 VAC ±10 %<br>50/60 Hz       |
| X19           | L2         |                                 |
| X20-GRD       | GRD        | Protective conductor connection |
| 480 V version |            |                                 |
| X18           | L1         | 480 VAC ±10 %<br>50/60 Hz       |
| X19           | L2         |                                 |
| X20-GRD       | GRD        | Protective conductor connection |

Table 9: Terminal assignment of the mains connection

|  |  |
|--|--|
| Version  | 3-pin connector with push-in spring connection |
| Rigid/flexible conductor cross-section (min/max)   | 1.5 mm <sup>2</sup> /2.5 mm <sup>2</sup>       |
| Stripped length  | 10 mm  |
| Flexible conductor cross-section with wire end ferrule with/without plastic sleeve (min/max) | 1.5 mm <sup>2</sup> /2.5 mm <sup>2</sup>       |
| AWG conductor cross-section (min/max)  | 15/12  |

Table 10: Connection data of the mains connection

Use copper cables only for the connection. For UL-compliant operation, design the cable insulation for a maximum temperature of 60 °C.

### 3.6.4 Internal fusing

| Designation | Function   | Fusing |
|-------------|--|--------|
| SI2         | Control section fuse (18 VAC)  | 4 A    |
| SI3         | Power section fuse (26 VAC)  | 15 A   |
| SI200       | Blade fuse, emergency power supply power section (only equipped with battery charging circuit) | 5 A    |

Table 11: Fuses of the TSG V4 electronic components

Fuses SI2 and SI3 are not replaceable. If they blow, it is only possible for the TSG V4 electronic components to be replaced by Langer & Laumann.

## 3.6.5 Inputs and outputs

### 3.6.5.1 Signal inputs (X1)

#### Connection of the signal inputs (X1)

The inputs for the "Open door" (X1.1), "Close door" (X1.2) and Reserve (X1.3) input signals are connected with a (nominal) voltage of 24 VDC. All inputs have a common potential, i.e., the same voltage must always be applied to all three inputs.

| Pin  | Assignment  |   |
|------|---|---|
| X1.1 | "Open door" input signal  | 16 VDC...28 VDC, min 10 mA  |
| X1.2 | "Close door" input signal   | 16 VDC...28 VDC, min 10 mA  |
| X1.3 | Input signal (reserve)  | 16 VDC...28 VDC, min 10 mA  |
| X1.4 | Counter potential für input signals   | (Common)  |
| X1.5 | Auxiliary voltage output +<br>Can only be used to control the TSG input signals X1.1, X1.2 and X1.3.            | 24 VDC $\pm 20\%$<br>— limited voltage<br>— not stabilised<br>— fluctuates with the mains voltage<br>— 300 mA max load capacity |
| X1.6 | Auxiliary voltage output +<br>For the supply of external devices. X1.6 is switched off in emergency power mode. | 24 VDC $\pm 20\%$<br>— limited voltage<br>— not stabilised<br>— fluctuates with the mains voltage<br>— 300 mA max load capacity |
| X1.7 | Auxiliary voltage output –  | 0 VDC   |
| X1.8 | Auxiliary voltage output –  | 0 VDC   |

Table 12: Terminal assignment of the signal inputs (X1)

The following table shows the connection and wiring options for the input signals X1.1 and X1.2.

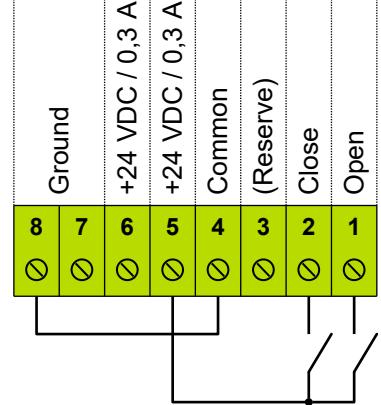
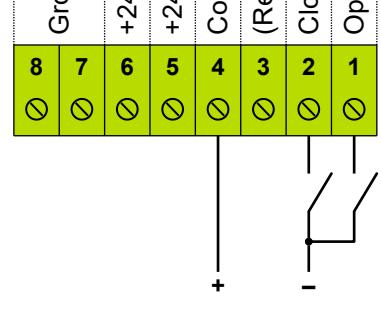
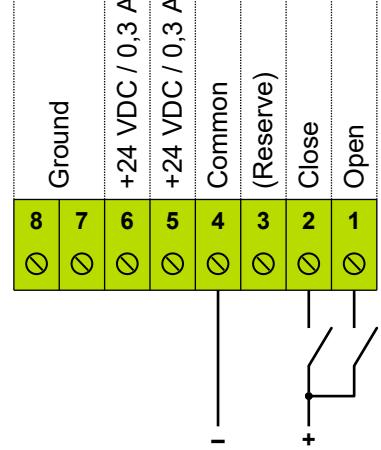
|  |   |
|--|---|
| With internal 24-VDC power supply                  |    |
| With external 24-VDC power supply and common plus  |   |
| With external 24-VDC power supply and common minus |  |

Table 13: Connection options for the input signals

|  |  |
|--|--|
| Version  | 8-pin connector with push-in spring connection |
| Rigid/flexible conductor cross-section (min/max)   | 0.2 mm <sup>2</sup> /2.5 mm <sup>2</sup>       |
| Stripped length  | 10 mm  |
| Flexible conductor cross-section with wire end ferrule with/without plastic sleeve (min/max)   | 0.25 mm <sup>2</sup> /2.5 mm <sup>2</sup>      |
| AWG conductor cross-section (min/max)  | 24/12  |
| 2 conductors with the same cross-section, flexible with TWIN-AEH with plastic sleeve (min/max) | 0.5 mm <sup>2</sup> /1.5 mm <sup>2</sup>       |
| AWG according to UL/CUL (min/max)  | 26/12  |

Table 14: Connection data of the signal inputs (X1)

Use copper cables only for the connection. For UL-compliant operation, design the cable insulation for a maximum temperature of 60 °C.

### ATTENTION

#### Possible damage

The auxiliary voltage output at X1.5/X1.6 may not be connected to an external voltage potential. If an external voltage potential is connected to X1.5/X1.6, this can irreparably damage the device.

### Standard operation of the signal inputs (X1)

In this mode, a signal applied to the respective input (X1.1, X1.2 or X1.3) is executed as long as it is applied. If the input signal is removed, the command is no longer executed.

If an input signal is applied to the two inputs X1.1 and X1.2 at the same time, then the door is opened.

If the door is to be completely opened or closed, the corresponding signal must be applied until the corresponding relay output (X2) is set.

Standard operation of the signal inputs is active if parameter **h1** is set to 00.

### Pulsed operation of the signal inputs (X1)

In this mode, a pulse at least 0.2 seconds long triggers the required action at the respective signal input.

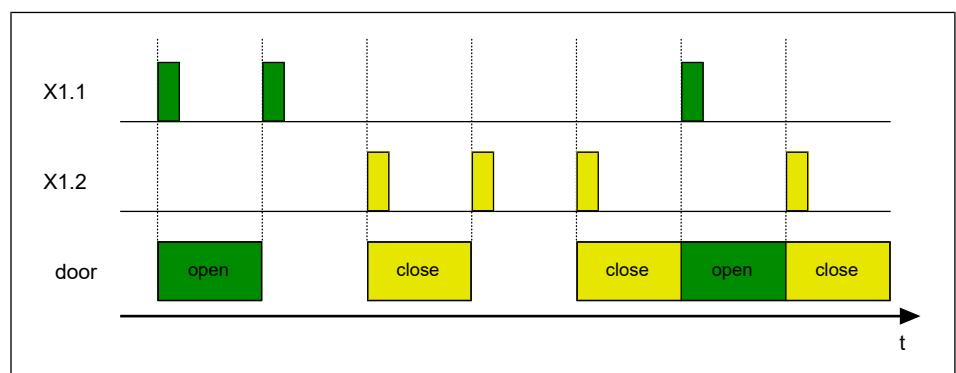
Pulsed operation of signal inputs X1.1 and X1.2 is active if parameter **h1** is set to 02, 03 or 04. Signal input X1.3 cannot be changed to pulsed operation and remains in standard operation.

**Variant 1** Variant 1 enables pulsed operation at inputs X1.1 and X1.2. To select variant 1, set parameter **h1** to 02.

If the closing force limitation triggers during closing the door stops. If it is to continue closing, the subsequent closing must be retriggered by a pulse at input X1.2. If automatic reversing is set (parameter **b4 = on**), the door opens completely. A new pulse must then be applied at input X1.2 to close the door.

If input X1.3 triggers reversing during closing, the subsequent closing must be retriggered by a pulse at input X1.2.

The following figure uses an example to show how the door is controlled over time by the application of pulses at inputs X1.1 and X1.2.



III. 10: Pulsed operation time sequence (variant 1)

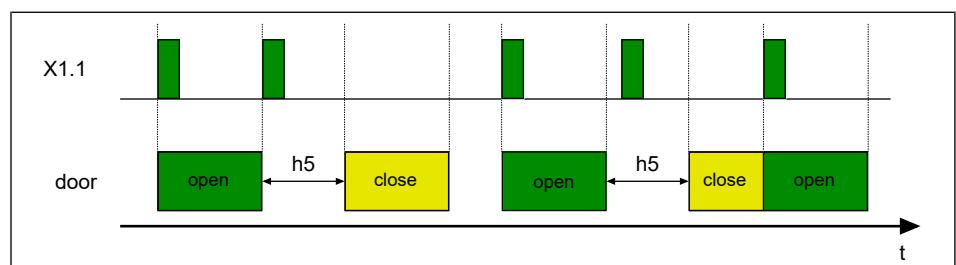
**Variant 2** Variant 2 enables pulsed operation at input X1.1, input X1.2 is deactivated. After the time set in parameter **h5**, the door is closed automatically in compliance with the closing force limitation set.

If the closing force limitation triggers during closing, the door stops. The closing starts again after around five seconds. If automatic reversing is set (parameter **b4 = on**), the door opens completely. The following closing is retriggered after the time set in parameter **h5** has expired.

If the door was opened by a pulse the remaining time in the open position is shown in the display.

If input X1.3 triggers reversing during closing, the following closing is triggered again after the time in parameter **h5** has expired. If the time set in parameter **h5** has expired and input X1.3 continues to trigger, then the door remains stopped in the open position until input X1.3 releases the door again.

The following figure uses an example to show how the door is controlled over time by the application of pulses at input X1.1.



III. 11: Pulsed operation time sequence (variant 2)

### 3.6.5.2 Relay outputs (X2)

Three relay outputs, each with a changeover contact, are present on the TSG V4 electronic components in order to display or signal the door statuses. The contacts are located on terminal block X2.

| Pin  | Assignment                                     |
|------|--|
| X2.1 | "Door open" output signal, potential supply    |
| X2.2 | "Door open" output signal, break contact       |
| X2.3 | "Door open" output signal, make contact        |
| X2.4 | "Door closed" output signal, potential supply  |
| X2.5 | "Door closed" output signal, break contact     |
| X2.6 | "Door closed" output signal, make contact      |
| X2.7 | "Door blocked" output signal, potential supply |
| X2.8 | "Door blocked" output signal, break contact    |
| X2.9 | "Door blocked" output signal, make contact     |

Table 15: Terminal assignment of the relay outputs (X2)

### Connection data

If relays/contactors are switched with the relay outputs, they must be equipped with a freewheeling diode for direct voltage and with an RC combination for alternating voltage.

|  |  |
|--|--|
| Version  | 9-pin connector with push-in spring connection |
| Rigid/flexible conductor cross-section (min/max)   | 0.2 mm <sup>2</sup> /2.5 mm <sup>2</sup>       |
| Stripped length  | 10 mm  |
| Flexible conductor cross-section with wire end ferrule with/without plastic sleeve (min/max)   | 0.25 mm <sup>2</sup> /2.5 mm <sup>2</sup>      |
| AWG conductor cross-section (min/max)  | 24/12  |
| 2 conductors with the same cross-section, flexible with TWIN-AEH with plastic sleeve (min/max) | 0.5 mm <sup>2</sup> /1.5 mm <sup>2</sup>       |
| AWG according to UL/CUL (min/max)  | 26/12  |
| Power data (UL/CSA)  |  |
| Make contact (NO)  | 1 A/50 VAC<br>1 A/24 VDC                       |
| Break contact (NC)   | 1 A/50 VAC<br>1 A/24 VDC                       |
| Power data (VDE)   |  |
| Make contact (NO)  | 1 A/230 VAC<br>1 A/230 VDC                     |
| Break contact (NC)   | 1 A/230 VAC<br>1 A/230 VDC                     |

Table 16: Connection data of the relay outputs (X2)

Use copper cables only for the connection. For UL-compliant operation, design the cable insulation for a maximum temperature of 60 °C.

## ATTENTION

### Possible damage

Voltages of different systems must not be connected to the relay outputs (e.g. 24 V and 80 V at the same time).

### 3.6.5.3 Connection for the stop function (X5)

#### ⚠ CAUTION



#### Risk of injury and possible damage from unintentional door movements

External voltage at terminals X5.1 or X5.2 can cause unintentional door movements or irreparable damage to the TSG V4 electronic components.

— Do not connect any external voltages to terminals X5.1 or X5.2.

The TSG V4 electronic components are equipped with a stop function (see ▶ *Stop function [p. 58]*). In normal operation and without use of the stop function there is a jumper wire between terminals X5.1 and X5.2.

After resetting the stop input, the door drive does not restart automatically by use of pulsed operation at input X1. The drive does not start until after the pulse at input X1 has been triggered.

If the stop function is triggered, the limit switches activated at X2 remain active as long as the door is in the respective end position.

| Pin  | Assignment             |                |
|------|------------------------|----------------|
| X5.1 | Potential-free contact | 0 VDC...24 VDC |
| X5.2 | Potential-free contact |                |

Table 17: Terminal assignment of the connection for the stop function (X5)

|  |  |
|--|--|
| Version  | 2-pin printed board terminal             |
| Rigid/flexible conductor cross-section (min/max)   | 0.5 mm <sup>2</sup> /1.5 mm <sup>2</sup> |
| Stripped length  | 5 mm                                     |
| Flexible conductor cross-section with wire end ferrule with/without plastic sleeve (min/max) | 0.5 mm <sup>2</sup> /1.5 mm <sup>2</sup> |
| AWG conductor cross-section (min/max)  | 20/15                                    |

Table 18: Connection data of the connection for the stop function (X5)

Use copper cables only for the connection. For UL-compliant operation, design the cable insulation for a maximum temperature of 60 °C.

## 3.6.6 Motor connection

### 3.6.6.1 Encoder connection (X3)

Version: 9-pin D-sub

| Pin   | Assignment    |                                 |                                 |                |
|-------|---------------|---------------------------------|---------------------------------|----------------|
| 1...4 | Not connected |                                 |                                 |                |
| 5     | Motor ID      |                                 |                                 |                |
|       |               | Cable core<br>(motor version K) | Cable core<br>(motor version K) | Motor terminal |
| 6     | GND           | Yellow                          | Brown                           | 1              |
| 7     | Channel B     | Green                           | White                           | 5              |
| 8     | Channel A     | Brown                           | Yellow                          | 3              |
| 9     | +5 VDC        | White                           | Green                           | 4              |

Table 19: Terminal assignment of the encoder (X3) with fixed cable on the motor

| Pin   | Assignment    | Pin at the encoder connector |
|-------|---------------|------------------------------|
| 1...4 | Not connected |                              |
| 5     | Motor ID      | 6                            |
| 6     | GND           | 4                            |
| 7     | Channel B     | 10                           |
| 8     | Channel A     | 2                            |
| 9     | +5 VDC        | 9                            |

Table 20: Terminal assignment of the encoder (X3) with plug-in cable set

#### ATTENTION

##### Possible damage

Before plugging in or unplugging the encoder connector, switch off the power supply.

### 3.6.6.2 Motor connection (X4)

Version: 2-pin screw/plug-in

| Pin | Assignment                           | Core colour |
|-----|--------------------------------------|-------------|
| 1   | Motor +                              | Brown       |
| 2   | Motor -                              | White       |
| X8  | Motor shield via cable lug 4.8 × 0.8 | Housing     |

Table 21: Terminal assignment of the motor connection (X4)

#### ATTENTION

##### Possible damage

- Before plugging in or unplugging the motor connection connector, switch off the power supply.
- Do not change the assignment of the motor connection. Incorrect assignment is detected by the TSG V4 electronic components and leads to an interruption in operation and an error message.

### 3.6.7 External control voltage

#### ATTENTION

##### Possible damage

- Only connect the external control voltage after consulting Langer & Lammann.

The control voltage supplied by the internal transformer can be replaced by an insulated connection on site. This external control voltage then supplies the logic of the TSG V4 electronic components and the encoder of the drive. The load section of the TSG V4 electronic components continues to be supplied by the mains connection. If an external control voltage is connected, the two cores of the internal power supply must then be removed from terminals X26 and X27 and properly insulated by the customer against short-circuit.

| Pin   | Assignment |  |
|---|------------|--|
| X26 ► <i>mains power connection of the TSG internal electronic components [p. 22]</i> | +          | 21.6 VDC...27.6 VDC or 16.2 VAC...20.0 VAC<br>3.9 A max.<br>The maximum fusing of the control circuit must not exceed 4 A. |
| X27 ► <i>mains power connection of the TSG internal electronic components [p. 22]</i> | —          |  |
| GRD   | GRD        |  |

Table 22: Terminal assignment of the connection for external control voltage

|  |  |
|--|--|
| Version  | 9-pin printed board terminal             |
| Rigid/flexible conductor cross-section (min/max)   | 0.5 mm <sup>2</sup> /1.5 mm <sup>2</sup> |
| Stripped length  | 5 mm                                     |
| Flexible conductor cross-section with wire end ferrule with/without plastic sleeve (min/max) | 0.5 mm <sup>2</sup> /1.5 mm <sup>2</sup> |
| AWG conductor cross-section (min/max)  | 20/15                                    |

Table 23: Connection data of the connection for external control voltage

Use copper cables only for the connection. For UL-compliant operation, design the cable insulation for a maximum temperature of 60 °C.

## 3.7 TSG options

On request, the TSG V4 is available with various extension options.

### 3.7.1 TSG web interface

With the optionally available additional TSG web interface electronic components and the TVis-Web software, the TSG V4 can be connected to a PC, notebook or tablet. The connection between a PC, notebook or tablet and the TSG web interface can, depending on the scope of supply, either be hard-wired or connected wirelessly via WLAN (WiFi).

TVis-Web is software for visualisation of the TSG V4, which can be started directly without installation with a browser (e.g. Microsoft Edge or Mozilla Firefox).

The system supports the following functions:

- Monitoring TSG V4 (remote control, travel profile display, error memory, ...)
- Settings (parameter changes, additional settings, ...)
- System settings (IP address, door values, export/import of the parameters, ...)

For further information see *TVis-Web documentation (1.20.91500)*.

### 3.7.2 Emergency power supply

The TSG V4 electronic components are available with an optional emergency power supply. The emergency power supply consists of a unit additionally attached to the TSG V4 electronic components and two NiMh rechargeable batteries.

With the emergency power supply, the door can be opened and closed in case of a power failure. The number of journeys and the speed depend on the weight and ease of movement of the traversing door. A reduced speed is generally to be expected. If the mains power at the TSG V4 electronic components has been restored, it switches to normal mode.

If the two batteries are connected correctly, detected by the TSG V4 electronic components and are ok, the dot of the right-hand 7-segment display flashes every second when a mains voltage is applied while the batteries are being charged. If both batteries are completely charged, the TSG V4 electronic components switch to trickling charge mode and the dot is lit continuously.

If the batteries are connected and there is no mains voltage, the dot in the right-hand 7-segment display flashes every 0.5 seconds. If the batteries are exhausted, the TSG V4 and the display are completely switched off (see also ▶ [7-segment display \[p. 39\]](#)).

If the mains supply and connected batteries fail, no voltage is applied to terminal X1.6.

### 3.7.3 Light curtain

To monitor the door area, the TSG V4 can be equipped with a light curtain (TSG light kit). The light curtain consists of a transmitter and receiver bar and monitors the door entrance area. To simplify the mounting, the TSG light kit is equipped with plug-in cables. The mounting time for connecting the electrical part is thus shortened significantly.

The signals arriving from the light curtain can either be evaluated by the lift control system or directly by the TSG V4.

If the TSG V4 is controlled directly by the light curtain, input X1.3 is used for signal processing. To this end, the parameter ***h3*** must be configured accordingly (see also ▶ [User setting of the \*h\* parameter \[p. 48\]](#)). The signal of the light cur-

tain can be optionally evaluated as "low active" or as "high active". If a signal for opening the door from the light curtain is applied to the TSG V4, the door is opened as long as the light curtain is interrupted.

After a mains power failure and return, the door remains open if the light curtain sends an open signal and the door is not yet referenced.

A control signal at input X1.3 is disregarded by the TSG V4 if the door is within the area of parameter **bb** (capture range for "closed" position, see also ▶ [Using setting of the b parameters \[p. 47\]](#)). The light curtain may not be connected to input X1.3.

For further information see *TSG Light Kit documentation*.

## 4 Transportation and storage

### ATTENTION

#### Possible damage

Improper transport and improper storage can damage the TSG V4.

- Only transport and store the device in the original packaging.
- Do not remove the required components from the packaging until just before they are mounted.

### 4.1 Transportation

Check the delivery to ensure it is complete and intact. If you identify any transportation damage or if the delivery is not complete, please inform your distributor.

### 4.2 Packaging

Environmentally friendly materials only are used for the packaging. Packaging materials are valuable raw materials and can be reused and recycled. Therefore, add the packaging materials to the recycling cycle. Where this is not possible, dispose of the packaging materials according to the local regulations.

### 4.3 Storage

Store the TSG V4

- in the original packaging
- not outdoors
- dry, frost and dust-free
- protected against aggressive media and direct sunshine

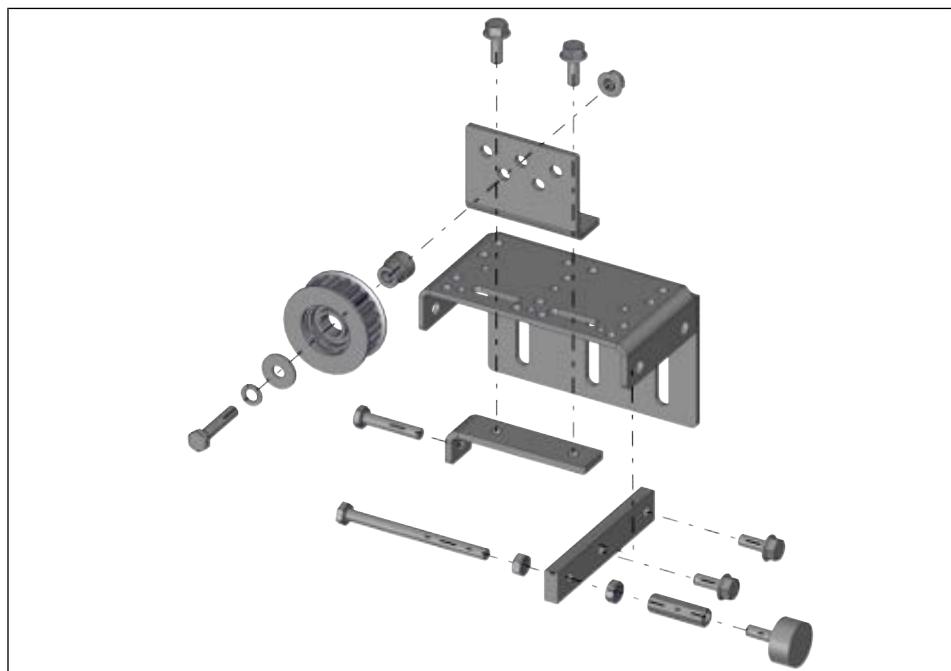
## 5 Mechanical mounting

### 5.1 Requirements

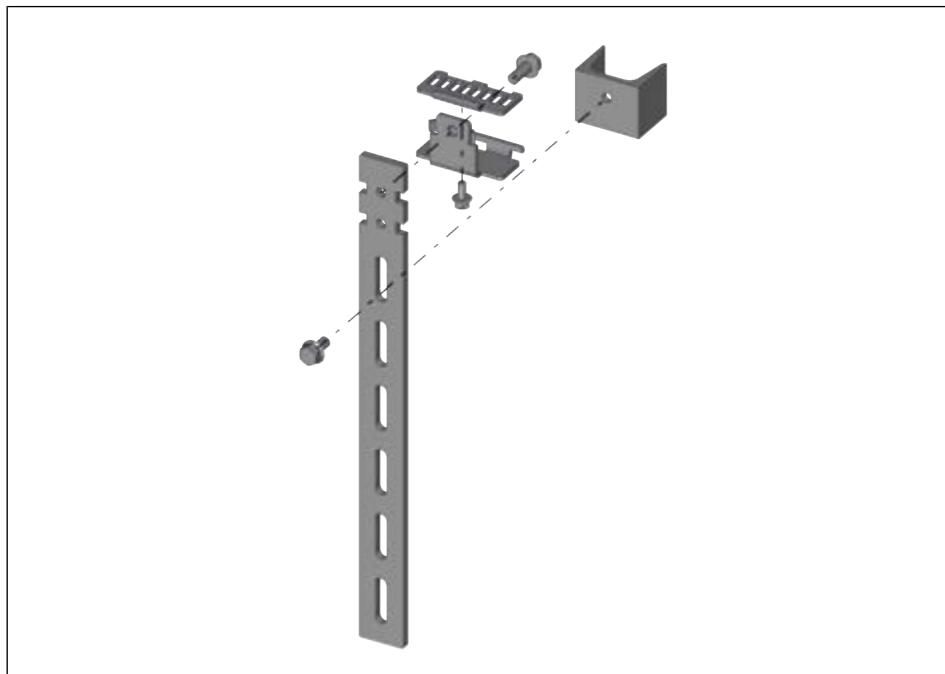
- The door must have fixed mechanical end stops for the “open” and “closed” positions, which withstand the applied energy of the TSG V4
- The end stops must be in the immediate vicinity of the timing belt.
- Any closing weight present must not jump.
- The doors must be easy moving.
- Do not install any additional springs (tension or compression springs) in the movement path of the door. Springs and/or dampers that were necessary for door drives used to date must be removed when installing the TSG V4.

### 5.2 Procedure

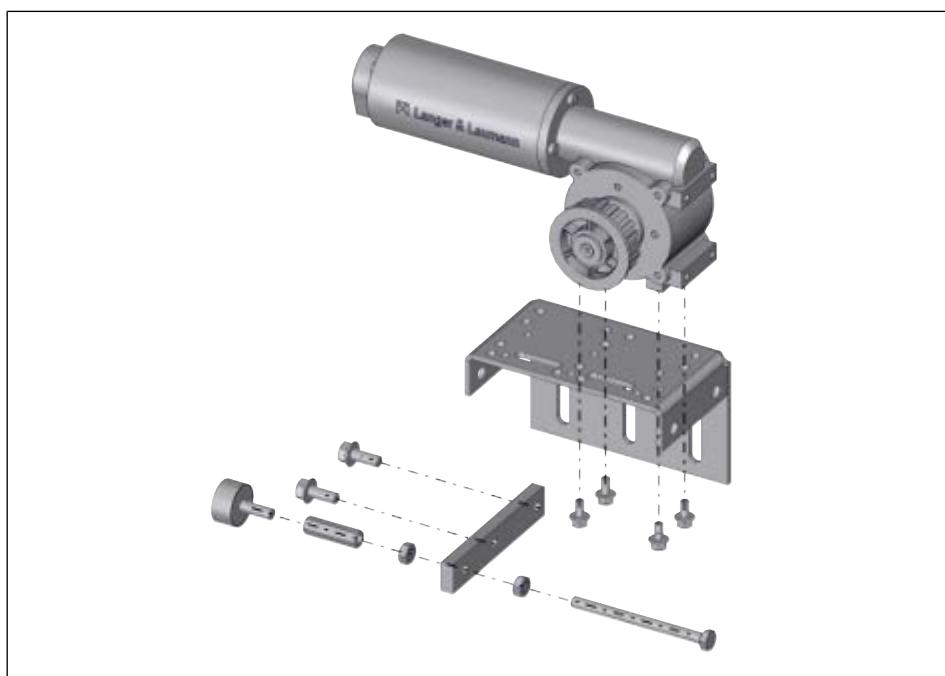
#### 5.2.1 Assembly



III. 12: Assembly of the deflection unit



III. 13: Assembly of the coupler unit



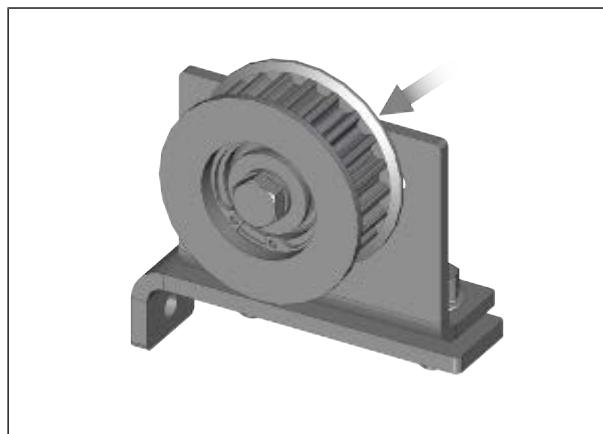
III. 14: Assembly of the drive unit

### 5.2.2 Mounting on the door

1. Mount the motor of the door drive. It is not important whether the motor is mounted on the open or close side of the door, as the correct travel direction is determined when measuring.
2. Mount the deflection pulley and the tensioning station.
3. **ATTENTION**  
**Only use the TSG timing belt locks as timing belt lock (door mounting). Unsuitable mountings can exert a notch effect on the timing belt, which leads to premature tearing of the timing belt.**  
Fit the timing belt and connect with the timing belt lock.
4. Tighten the timing belt.
5. Mount the door panel coupler on the fastest door panel and on the timing belt lock.
6. If no fixed stops are present, mount buffers on the combined bracket. Screw the C-profile at a suitable height onto the door panel coupler as a mating part.
7. Securely attach the TSG V4 with housing near the drive. Make sure that the motor and encoder cables can be connected with sufficient clearance at the TSG V4 electronic components.
8. Connect the 9-pin D-sub connector with socket X3 on the TSG V4 electronic components. Plug the motor cable onto terminal block X4 and the shielded terminal of the motor cable on terminal X8 on the TSG V4 electronic components.

### 5.3 Deflection pulley

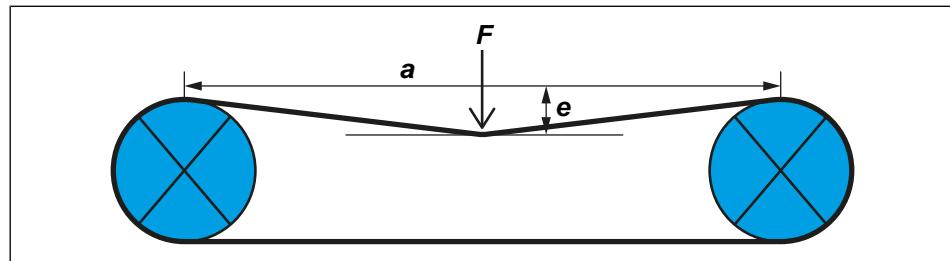
When mounting the deflection pulley, make sure that it is fixed with the side of the pressed on flanged washer in the direction of the bracket.



III. 15: Deflection pulley mounted

## 5.4 Timing belt

The timing belt must be tightened with a specified timing belt tension. This ensures optimum force transfer and protection of the timing belt and the bearing.

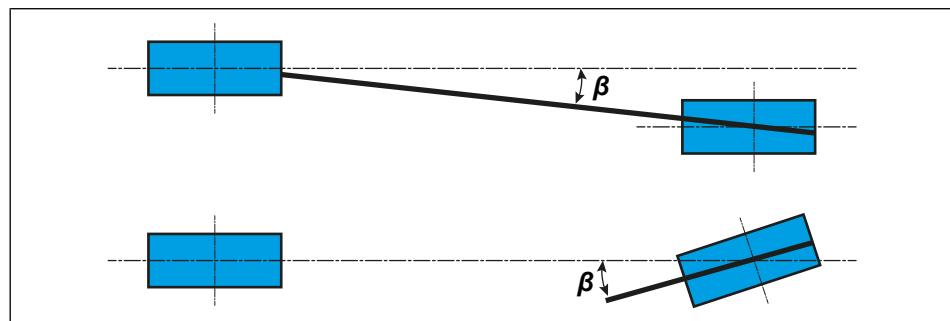


III. 16: Determination of the timing belt tension

At a centre-to-centre spacing  $a$  of 1 m (centre-to-centre of the axes), the deflection  $e$  should be 16 mm and the force  $F$  18.5 N.

If the timing belt tension is too low it can cause premature wear of the toothing on the timing belt. In addition, the timing belt can jump on the drive gear or the gear at the deflection pulley and therefore cause a changed position of the door. If the timing belt is too high, the load on the bearing is increased, the door drive power is reduced and leads to premature wear of the toothing on the timing belt.

The timing belt pulleys (motor and deflection pulley) must be aligned for good alignment. Equally, the shaft parallelism must be checked. The angle deviation must not exceed  $\beta = 0.7^\circ$ .



III. 17: Timing belt alignment

If the maximum angle deviation is exceeded the timing belt can rub against the flanged washers and can cause damage and premature wear to the timing belt edge. In addition, the uneven loading of the tension strand which impairs the life considerably.

## 6 Electric setting, parameterisation and commissioning

### 6.1 Overview

This section describes the diverse setting options of the TSG V4.

The settings of the parameters and the allowable closing forces (kinetic energy, static force) on the main and secondary closing edges must be checked and recorded by the skilled person carrying out the work after the commissioning or after changing parameters (see also ▶ [Setting the force limitation \[p. 55\]](#)).

### 6.2 7-segment display

On the TSG V4 electronic components there is a two-digit 7-segment display to show the applied state and to present the menu with the parameters and their values.

| Display   | Meaning   |
|---|---|
|    | No control is present.  |
|   | The TSG is not measured, manual measuring is required.<br>If the TSG V4 electronic components detect an incorrect motor or an incorrect motor connection, the display flashes and a measurement is not possible (see also ▶ <a href="#">Manual measuring [p. 41]</a> ). |
|  | The “open” signal is applied.   |
|  | The “close” signal is applied.  |
|  | The door is open.   |
|  | The door is closed.   |
|  | The door is blocked.  |
|  | An intermediate position has been reached (see also ).  |
|  | The reversing distance has been reached (parameter <b>bd</b> , see also ▶ <a href="#">Using setting of the b parameters [p. 47]</a> )   |
|  | Triggering of the stop function (see also ▶ <a href="#">Stop function [p. 58]</a> )   |
|  | Triggering of the light curtain (▶ <a href="#">Light curtain [p. 32]</a> )  |

Table 24: Display

The 7-segment display switches off automatically if the jog wheel is not used for 30 minutes. The display is switched on again by turning or pressing the jog wheel.

The two-digit 7-segment display can display up to three-digit values. The front and rear part of the number to be displayed are displayed alternately every second. Two-digit values are displayed without cycling.

**Example** The parameter **A.C** contains the value 172. The display shows " \_ /" for a second and "72" in the next second.

If the optionally available emergency power supply is installed, then the dot in the right-hand part of the display informs about the operating state.

### Emergency power supply status display

| Dot in right-hand part    | State                   | Description   |
|---------------------------|-------------------------|---|
| Off                       | TSG V4 is switched off. | Mains power voltage not available and batteries exhausted or not connected.                   |
| Flashes (0.5 s intervals) | Battery mode            | Mains power supply not available and the batteries supply the TSG V4 electronic components.   |
| Flashes (1 s intervals)   | Charging mode           | Mains power supply available, batteries are being charged.                                    |
| Lights up                 | Trickle charging mode   | Mains power supply available, batteries are charged, charge is maintained (trickle charging). |

Table 25: Emergency power supply status display

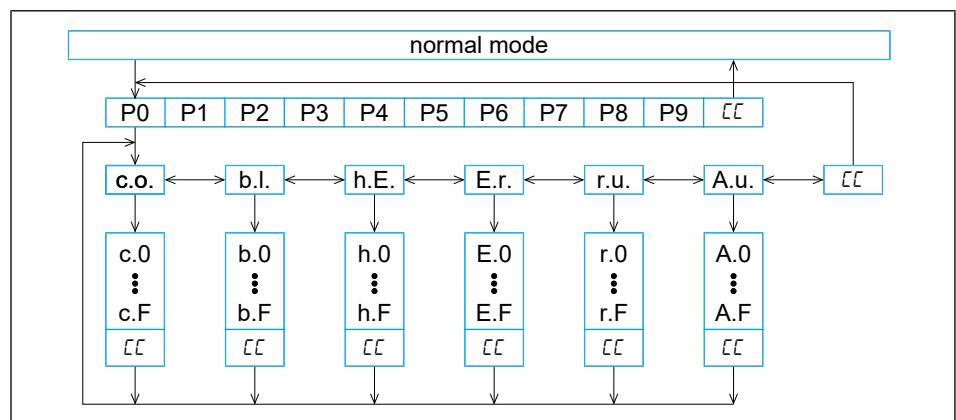
## 6.3 Menu structure

The TSG V4 is operated and set with a jog wheel located on the TSG V4 electronic components.

Pressing the jog wheel once from normal mode displays the menu start item "*P0*". Turning the jog wheel clockwise displays the next higher menu item, turning it counterclockwise displays the next lower menu item. Briefly pressing the jog wheel causes a jump to the displayed menu item. If the jog wheel is pressed briefly while "*EE*" is displayed the display switches to the next higher menu level. Pressing the jog wheel for around five seconds opens setting mode in which the parameter values can be changed by turning the jog wheel. If the required value is displayed, the setting mode is ended by briefly pressing the jog wheel.

If a value is set and saved by pressing the jog wheel, an internal check of successful adoption of the value takes place. If the adoption of the value was not successful, the operator's attention is drawn to this fact by the flashing of the display.

All parameters are saved permanently and are still present after a power failure.



III. 18: Menu structure

## 6.4 Manual measuring

### ⚠ CAUTION



#### Risk of injury

After successful ending of the measuring journey the drive is completely ready.

- During the measuring journey, keep parts of your body away from all moving parts.

After the mechanical mounting, a manual measurement of the TSG V4 must be carried out. At the same time, make sure that the door can close and open unobstructed and thus the determined data are not distorted. The door must not be obstructed by objects or sluggishness.

After each mechanical change (for example, tensioning of the timing belt, adjustment of the end stops or buffers), the travel distance can change. Therefore, after each change of the mechanics, a new manual measurement is required.

## Preparation for the first commissioning

1. Make sure that the mains power supply is switched off on the input side.
2. Make sure that the connectors X1 (inputs) and X2 (relay outputs) are not plugged into the TSG V4 electronic components.
3. Plug the TSG motor cable onto terminal block X4, the shielded terminal of the TSG motor cable onto terminal block X8 and the encoder cable onto terminal block X3.
4. Switch on the mains power supply (input side) at the TSG V4.

## Procedure

1. Use your hand to push the door roughly into the middle of the travel distance.
2. Use the jog wheel to select the parameter **P9**. Keep the jog wheel pressed for around five seconds. The preset value of the total weight of the component to be moved (door panels, guard) appears. Turn the jog wheel to set the correct total weight of the component to be moved in increments of 10 kg, note ▶ [Table 26 \[p. 42\]](#). For telescopic doors, only half the weight of the second door panel that is half as much slower is added to the weight. If the correct value is displayed, briefly press the jog wheel to confirm.

⇒ " /r" appears in the display.

| Display | Total weight [kg] |
|---------|-------------------|
| "0 /"   | 10                |
| "02"    | 20                |
| ...     | ...               |
| "99"    | 990               |

Table 26: Weight input

### ATTENTION

If the wrong position has been selected for the "Open" direction and the "Open" position has already been saved, then it is no longer possible to reverse the travel direction with the jog wheel. The measuring must be continued to the end and then a new measurement started.

3. Select the "open" direction first by turning the jog wheel in one direction. If the door moves in the "Close" direction instead of the "Open" direction, then turn the jog wheel in the opposite direction to reverse the direction of movement of the drive.
  - ⇒ If the door has reached and saved the "open" position, the door moves to the "closed" position automatically.
- ⇒ If the "Close" position is reached and the "cd" display is shown, then the measuring is successfully completed and the connectors X1 (inputs) and X2 (relay outputs) can be plugged in.
- ⇒ If "nL" appears in the display, the measuring was not successful and must be repeated. If an error message is displayed, the fault must be removed first (see ▶ [Troubleshooting \[p. 64\]](#)).

If the parameters are reset to standard with the parameter **EE**, the last set weight is retained. Renewed input of the weight is only possible with subsequent manual measuring.

## 6.5 Manual mode/manual travel

1. Use the jog wheel to select the parameter **P1**.  
⇒ "Hd" appears in the display.
2. Turn the jog wheel counterclockwise and the "-o" display appears. If the jog wheel is pressed and held, the door then moves in the "Open" direction. Turn the jog wheel clockwise and the "-c" display appears. If the jog wheel is pressed and held, then the door moves in the "Close" position. Let go of the jog wheel to stop the door.
3. To end manual mode, turn the jog wheel until the "Hd" display appears and then press the jog wheel.

Moving in manual mode corresponds to the same travel behaviour caused by applying input signals to terminals X1.1 or X1.2.

As long as the TSG V4 is in manual mode, input signals at terminals X1.1 and X1.2 are ignored. If the jostle function is activated (**h3 = 03**), this function can be carried out by applying the input signal at terminal X1.3 and at the same time, manual travel in the "Close" direction. If the TSG V4 is to be moved again via input signals at terminal block X1, manual mode must be ended.

If the stop function is activated in manual mode the manual mode is then ended. If an error occurs in manual mode the manual mode is also ended. It cannot be reactivated until the error has been removed.

As long as the TSG V4 is in manual mode, LED 10, LED 11 and LED 12 continue to indicate the applied input signals (► *Interfaces and displays of the TSG V4 electronic components [p. 18]*); however, the input signals are ignored.

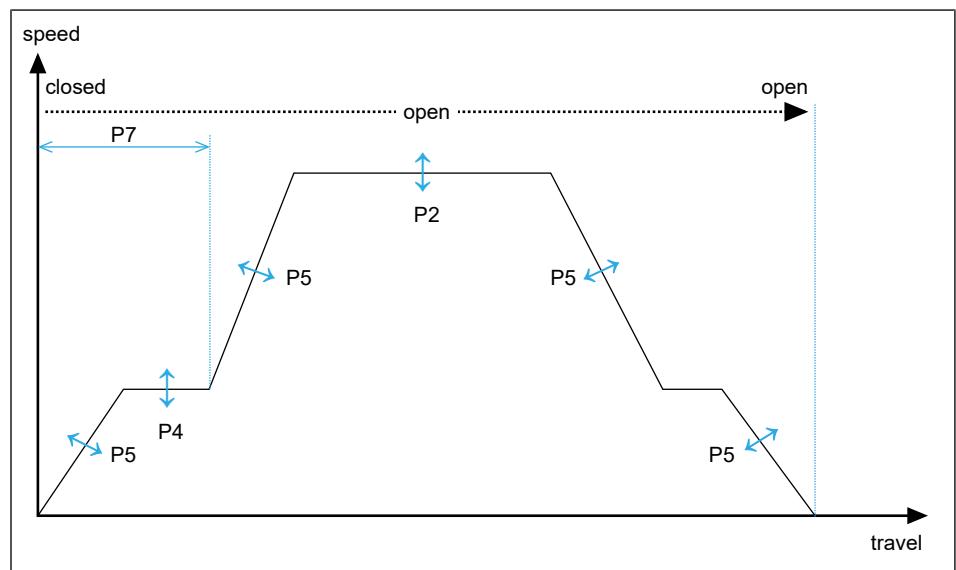
## 6.6 Standard parameters

### 6.6.1 Basic setting

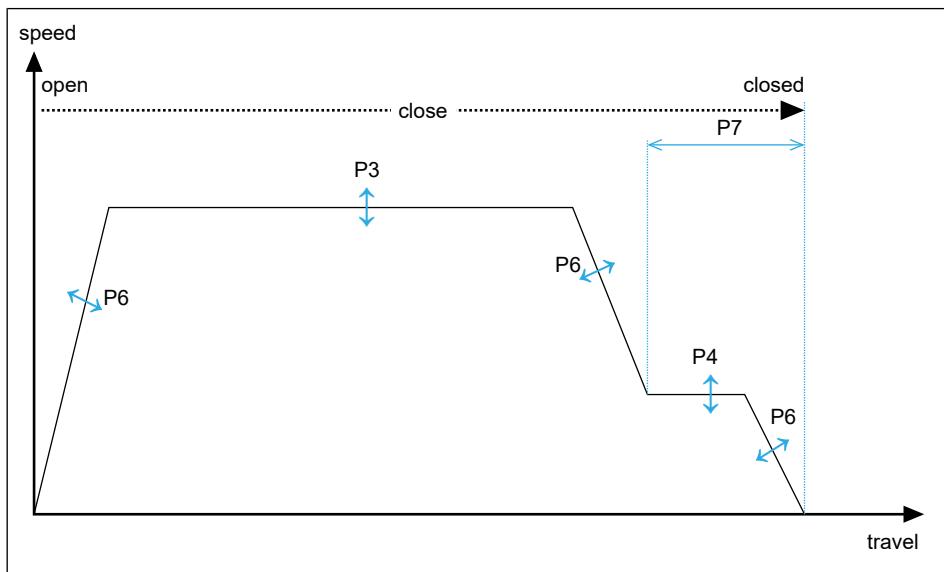
The TSG V4 is delivered with an executable basic setting, which generally does not have to be changed.

### 6.6.2 Travel profiles with default parameters

The following diagrams show schematically which parameters affect which sections of the travel profiles.



III. 19: "Open" travel profile with default parameters



III. 20: "Close" Travel profile with default parameters

### 6.6.3 User setting of the P parameters

The default parameters (P parameters) enable fast adjustment of the most important properties of the TSG V4 and thus fast setting of the travel values.

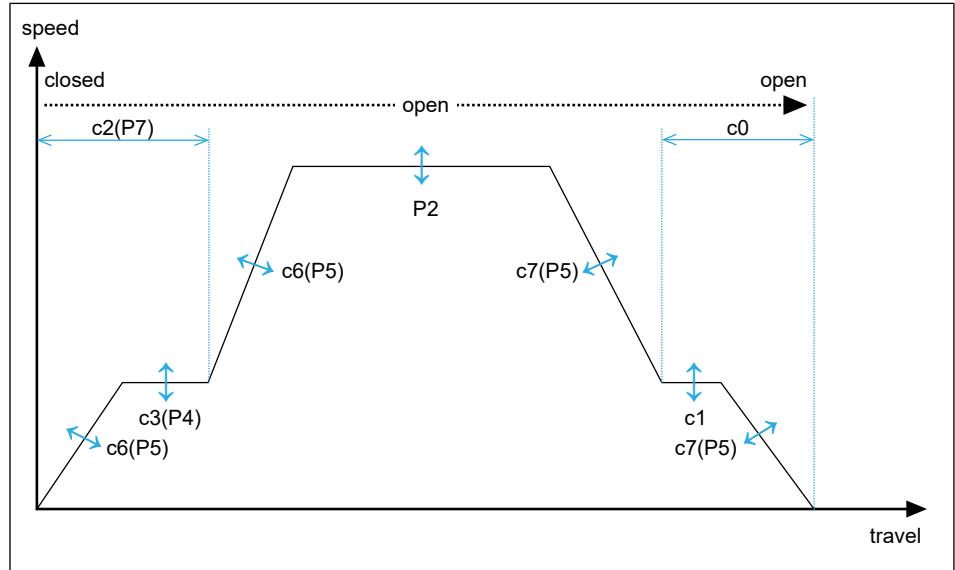
| Par.      | Function   | Note   | Min | Standard | Max       | Factor | Unit             |
|-----------|--|--|-----|----------|-----------|--------|------------------|
| <b>P0</b> | Access to the extended menu                              | See also ▶ <a href="#">Extended parameters [p. 45]</a>       |     |          |           |        |                  |
| <b>P1</b> | Manual mode  | See also ▶ <a href="#">Manual mode/manual travel [p. 43]</a> |     |          |           |        |                  |
| <b>P2</b> | Maximum opening speed                                    |  | 01  | 50       | 99        | 0.01   | m/s              |
| <b>P3</b> | Maximum closing speed                                    |  | 01  | 30       | 99        | 0.01   | m/s              |
| <b>P4</b> | Locking and unlocking speed                              | Creep speed just before the end position (closed)            | 01  | 05       | <b>P3</b> | 0.01   | m/s              |
| <b>P5</b> | Acceleration and braking in the opening direction        |  | 01  | 03       | 50        | 0.1    | m/s <sup>2</sup> |
| <b>P6</b> | Acceleration and braking in the closing direction        |  | 01  | 03       | 50        | 0.1    | m/s <sup>2</sup> |
| <b>P7</b> | Locking and unlocking distance                           | Creep distance just before the end position (closed)         | 00  | 03       | 99        | 1      | cm               |
| <b>P8</b> | "Blocked detection" threshold value in closing direction |  | 0.1 | 4.0      | 9.9       | 1      |                  |
| <b>P9</b> | Activating reference journey                             | See also ▶ <a href="#">Manual measuring [p. 41]</a>          |     |          |           |        |                  |
| <b>CC</b> | Ext the current level of the menu.                       |  |     |          |           |        |                  |

Table 27: P parameters

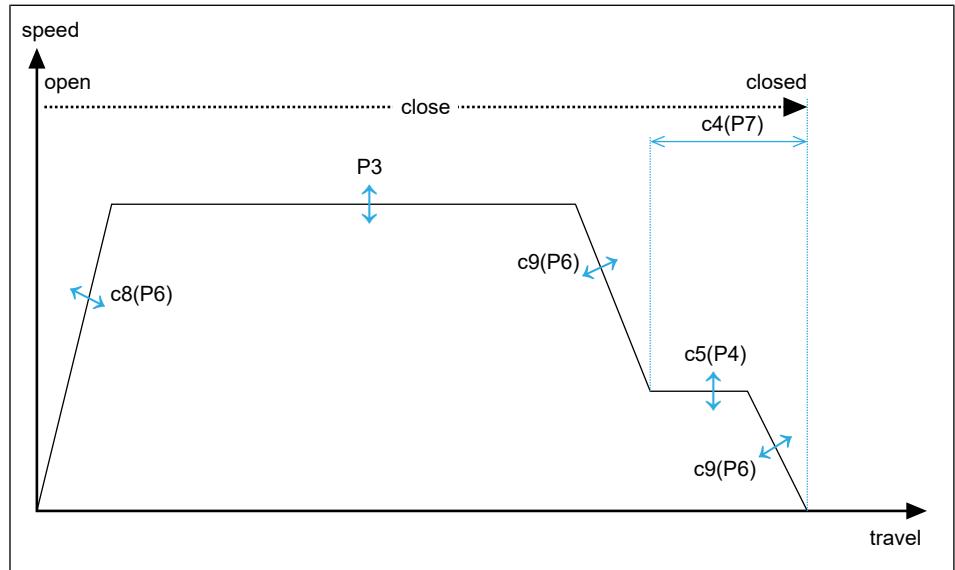
## 6.7 Extended parameters

### 6.7.1 Travel profiles with extended parameters

The following diagrams show schematically which parameters affect which sections of the travel profiles.



III. 21: “Open” travel profile with extended parameters



III. 22: “Close” Travel profile with extended parameters

## 6.7.2 User setting of the c parameters

The travel values can be set using the c parameters to adjust the travel values individually to the respective use case. It must be noted that when some P parameters are changed, several c parameters are also changed at the same time. This means that the value to which a P parameter is set is automatically entered in the corresponding c parameter.

| Par.      | Function   | Note | Min | Standard | Max                                       | Factor | Unit             |
|-----------|--|------|-----|----------|---|--------|------------------|
| <b>c0</b> | Creep distance length in opening direction                               |      | 00  | 02       | (internal calculation)                    |        | cm               |
| <b>c1</b> | Creep speed in opening direction   |      | 01  | 05       | 0,25 or <b>P2</b> : opening speed         | 0.01   | m/s              |
| <b>c2</b> | Length of the unlocking distance in the opening direction                |      | 00  | 03       | (internal calculation)                    |        | cm               |
| <b>c3</b> | Unlocking speed in the opening direction                                 |      | 01  | 05       | 0,25 or <b>P2</b> : opening speed         | 0.01   | m/s              |
| <b>c4</b> | Length of the locking distance in the closing direction                  |      | 00  | 03       | (internal calculation)                    |        | cm               |
| <b>c5</b> | Locking speed in the closing direction                                   |      | 01  | 05       | 0.25 or <b>P3</b> : maximum closing speed | 0.01   | m/s              |
| <b>c6</b> | Acceleration in the opening direction                                    |      | 01  | 03       | 50  | 0.1    | m/s <sup>2</sup> |
| <b>c7</b> | Deceleration in the opening direction                                    |      | 01  | 03       | 50  | 0.1    | m/s <sup>2</sup> |
| <b>c8</b> | Acceleration in the closing direction                                    |      | 01  | 03       | 50  | 0.1    | m/s <sup>2</sup> |
| <b>c9</b> | Deceleration in the closing direction                                    |      | 01  | 03       | 50  | 0.1    | m/s <sup>2</sup> |
| <b>cC</b> | Holding torque in opening direction without the "Open door" input signal |      | 0.0 | 1.0      | 2.5                                       |        | A                |
| <b>cd</b> | Holding torque in closing direction without "Close door" input signal    |      | 0.0 | 1.0      | 2.5                                       |        | A                |
| <b>cE</b> | Holding torque in opening direction with "Open door" input signal        |      | 0.0 | 1.0      | 2.5                                       |        | A                |
| <b>cF</b> | Holding torque in closing direction with "Close door" input signal       |      | 0.0 | 1.0      | 2.5                                       |        | A                |
| <b>CC</b> | Ext the current level of the menu.                                       |      |     |          |   |        |                  |

Table 28: c parameters

### 6.7.3 Using setting of the b parameters

| Par.      | Function   | Note  | Min       | Standard  | Max       | Factor | Unit |
|-----------|--|---|-----------|-----------|-----------|--------|------|
| <b>b2</b> | Threshold value for obstacle detection in the closing direction                                    | Closing force measurement   | 2.0       | 4.0       | 9.9       |        | A    |
| <b>b3</b> | Reaction of the "Door blocked" relay output in the closing direction                               | <p><b>oF:</b> continuously<br/><b>on:</b> pulse</p> <p>On activating the threshold value for obstacle detection in the closing direction the "Door blocked" output is set. The "Door blocked" output is reset when the "Open" position is reached.</p>  | <b>oF</b> | <b>oF</b> | <b>on</b> |        |      |
| <b>b4</b> | Reaction of the door drive in case of blocking in the closing direction                            | <p><b>oF:</b> if the door is blocked, the drive stops immediately. Opening of the door if the input signal changes to "Open door".</p> <p><b>on:</b> automatic reversing also with "the "Close door" input signal until the "open" position is reached. If the "Close door" input signal is still applied the door then closes again immediately. The parameter <b>h5</b> can be used to set the hold-open time (► <i>User setting of the h parameter [p. 48]</i>).</p> | <b>oF</b> | <b>oF</b> | <b>on</b> |        |      |
| <b>b5</b> | Activation of the blocked detection in the opening direction                                       | <p><b>oF:</b> off<br/><b>on:</b> on</p>   | <b>oF</b> | <b>on</b> | <b>on</b> |        |      |
| <b>b6</b> | Blocked detection in the first 30 % of the opening distance  | <p><b>oF:</b> blocked detection off in the first 30 % of the opening distance</p> <p><b>on:</b> blocked detection on in the whole opening distance</p>  | <b>oF</b> | <b>on</b> | <b>on</b> |        |      |
| <b>b7</b> | Threshold value for the blocked detection in the opening direction                                 |   | 2.0       | 9.5       | 9.9       |        | A    |
| <b>b8</b> | Reaction of the "Door blocked" relay output in the opening direction                               | <p><b>oF:</b> continuously<br/><b>on:</b> pulse</p>   | <b>oF</b> | <b>on</b> | <b>on</b> |        |      |
| <b>b9</b> | Reaction of the door drive in case of blocking in the opening direction                            | <p><b>oF:</b> if the door is blocked, the drive stops immediately. Closing of the door when the input signal changes to "Close door".</p> <p><b>on:</b> automatic reversing even with "Open door" input signal until the "closed" position is reached. If the "Open door" input signal is still applied the door then opens again immediately.</p>  | <b>oF</b> | <b>oF</b> | <b>on</b> |        |      |
| <b>bA</b> | Length of the output pulse at the "Door blocked" relay output in the opening and closing direction | Only effective if <b>b3</b> and/or <b>b8 = on</b>   | 0.1       | 1.0       | 2.0       |        | s    |
| <b>bb</b> | Capture range for the "door closed" position   | The obstacle detection is not active in this area.  | 01        | 05        | 50        |        | mm   |
| <b>bc</b> | Capture range for the "door open" position   | The obstacle detection is not active in this area.  | 01        | 10        | 50        |        | mm   |

| Par.  | Function                           | Note  | Min | Standard | Max | Factor | Unit |
|---|------------------------------------|---|-----|----------|-----|--------|------|
| <b>bd</b>   | Reversing distance                 | Effective for obstacle detection and sensor monitoring.   | 00  | 99       | 99  |        | cm   |
| <b>Obstacle detection</b>   |                                    |   |     |          |     |        |      |
| If the door is blocked, the TSG V4 reverses by the set value. If the value is set to 00 or 99, complete reversing takes place.          |                                    |   |     |          |     |        |      |
| Only active if the parameter <b>b4</b> or <b>b9</b> has been activated. The smallest reversing distance to be carried out is 5 cm.      |                                    |   |     |          |     |        |      |
| <b>Sensor monitoring</b>  |                                    |   |     |          |     |        |      |
| If the sensor is triggered on closing, the TSG V4 reverses by the set value. If the value is set to 99, complete reversing takes place. |                                    |   |     |          |     |        |      |
| The smallest reversing distance to be carried out is 5 cm.  |                                    |   |     |          |     |        |      |
| <b>bE</b>   | Slow movement to blocked position  | If the door was blocked in the closing direction, the TSG V4 moves slowly to the blocked position with the next closing movement. | off | on       | on  |        |      |
| <b>CC</b>   | Ext the current level of the menu. |   |     |          |     |        |      |

Table 29: b parameters

#### 6.7.4 User setting of the h parameter

| Par.  | Function   | Note | Min | Standard | Max | Factor | Unit |
|---|--|------|-----|----------|-----|--------|------|
| <b>h0</b>   | Continuous test:<br>Open door/close door/<br>bus system baud rate<br>setting |      | 00  | 00       | 04  |        |      |
| The door opens and closes continuously. The input signals at X1 are ignored. There is a pause of 5 seconds between the individual travel movements.   |  |      |     |          |     |        |      |
| If <b>hA</b> = 09, 10, 16, 17 or 18: setting of the baud rate in operation with bus system. In "Control by means of bus system" mode the parameter <b>h0</b> has a different meaning, see accompanying manual for the respective TSG option.  |  |      |     |          |     |        |      |
| <b>h1</b>   | Inputs and outputs setting/door number bus system setting                    |      | 00  | 00       | 03  |        |      |
| 00: has no function<br>01: test operation of the inputs and outputs<br>— Input X1.1 switches relay output X2.2 or X2.3<br>— Input X1.2 switches relay output X2.5 or X2.6<br>— Input X1.3 switches relay output X2.8 or X2.9<br>02: pulsed mode of inputs X1.1 and X1.2 (pulse length at least 0.2 s).<br>03: pulsed mode of input X1.1 (pulse length at least 0.2 s). Input X1.2 is not evaluated. When the pulse is applied the door opens completely and closes automatically after the time set with <b>h5</b> has expired.<br>If <b>hA</b> = 09, 10, 16, 17 or 18: setting of the door number in operation with bus system. In "Control by means of bus system" mode the parameter <b>h1</b> has a different meaning, see accompanying manual for the respective TSG option. |  |      |     |          |     |        |      |
| <b>h2</b>   | Leading limit switch   |      | 00  | 00       | 31  |        |      |
| The relay outputs for "Door open" or "Door closed" (terminal block X2) can be set to be leading. In keeping with the configuration, they switch before the teached-in end position has been completely reached (see ▶ <a href="#">Leading limit switch [p. 59]</a> ).   |  |      |     |          |     |        |      |

| Par.             | Function  | Note  | Min | Standard | Max | Factor | Unit    |
|------------------|---|---|-----|----------|-----|--------|---------|
| <b><i>h3</i></b> | Input X1.3 function   | <p>00: stop function (see ▶ <a href="#">Stop function [p. 58]</a>)<br/>     01: light curtain "high active" (if LED 12 lights up the door opens)<br/>     02: light curtain "low active" (if LED 12 goes out the door opens)<br/>     03: closing of the door if protective device is deactivated or failed (see ▶ <a href="#">Closing the door on deactivation or failure of the external protective device [p. 57]</a>).<br/>     04: reserved<br/>     05: stop function, the door stops if the input signal is interrupted.<br/>     06: has no function<br/>     07: TSG connection set, light grid mode<br/>     The parameter <b><i>h3</i></b> is <b>not</b> reset to default on loading the default settings (see also ▶ <a href="#">Error with displayed error code [p. 65]</a>).<br/>     If the parameter <b><i>h3</i></b> is set to 01, 02 or 07, the reversing <b>distance</b> can be set via the parameter <b><i>bd</i></b> and the reversing <b>time</b> via parameter <b><i>h5</i></b>.</p> | 00  | 00       | 07  |        |         |
| <b><i>h4</i></b> | In "Control by means of bus system" mode the parameter <b><i>h4</i></b> has a different meaning, see accompanying manual for the respective TSG option. |   |     |          |     |        |         |
| <b><i>h5</i></b> | Reversing time  |   | 00  | 00       | 99  |        | s       |
|                  |   | If the "Automatic reversing" function is active ( <b><i>b4</i></b> = <b>on</b> ) or "Pulsed operationX1.1" ( <b><i>h1</i></b> = 03), the door remains active for the set value. If the value is 00, the door closes again immediately. If the door is opened, the time is counted back and the remaining value is shown in the display.   |     |          |     |        |         |
| <b><i>h6</i></b> | Speed after return of mains power supply and speed while measuring.   | Speed on referencing the two end positions after voltage return and during the measuring (see also ▶ <a href="#">User setting of the P parameters [p. 44]</a> , P9).  | 01  | 15       | 25  | 0.01   | m/s     |
| <b><i>h7</i></b> | TSG sinus drive opening time  | Only if the optional additional TSG sinus drive circuit board is used, see parameter setting <b><i>hA</i></b> in the accompanying documentation.  | 00  | 50       | 80  |        | 1/100 s |
| <b><i>h8</i></b> | Force for checking end position in CLOSED   |   | 0.1 | 3.5      | 9.9 |        | A       |
| <b><i>h9</i></b> | Force for checking end position in OPEN   |   | 0.1 | 1.0      | 9.9 |        | A       |
| <b><i>hA</i></b> | Mode selection (see ▶ <a href="#">Mode setting with parameter <i>hA</i> [p. 50]</a> )   | Only if the corresponding optional additional circuit board is used.  | 00  | 00       | 99  |        |         |
| <b><i>hb</i></b> | TSG sinus drive closing time  | Only if the optional additional TSG sinus drive circuit board is used, see parameter setting <b><i>hA</i></b> in the accompanying documentation.  | 01  | 50       | 80  |        | 1/100 s |
| <b><i>hc</i></b> | Pause between opening the TSG sinus drive and the opening of the door   | Only if the optional additional TSG sinus drive circuit board is used, see parameter setting <b><i>hA</i></b> in the accompanying documentation.  | 01  | 50       | 499 |        | 1/100 s |

| Par.      | Function  | Note   | Min | Standard | Max | Factor | Unit |
|-----------|---|--|-----|----------|-----|--------|------|
| <b>hd</b> | Force for checking the end position when measuring in CLOSED                        | If the parameter is reduced, renewed measuring must then take place.   | 0.1 | 3.0      | 9.9 |        | A    |
| <b>hE</b> | Force for checking the end position when measuring and referencing in OPEN          | If the parameter is reduced, renewed measuring must then take place.   | 0.1 | 3.0      | 9.9 |        | A    |
| <b>hF</b> | Suppression of blocked detection in the last (maximum) 50 mm of the closing travel. | The maximum 50 mm is made up of the values of the parameters <b>bb</b> and <b>hF</b> .<br>Example: <b>bb</b> = 10 mm => <b>bb</b> = maximum 40 mm.<br>In The blocked detection is not active in this area. |     |          |     |        |      |
| <b>CC</b> | Ext the current level of the menu.  |  |     |          |     |        |      |

Table 30: h parameter

### 6.7.5 Mode setting with parameter hA

| Value hA | Function   | Accompanying documents  |
|----------|--|---|
| 00       | Operation of the TSG V4 without extension  |   |
| 01       | TSG sinus drive control  | 1.20.94090_xx_Instructions_Vx.x_TSG sinus drive   |
| 02       | reserved   |   |
| 03       | TSG sinus drive control with emergency power supply  | 1.20.94090_Instructions_Vx.x_TSG sinus drive  |
| 04       | reserved   |   |
| 05       | reserved   |   |
| 06       | TSG sinus drive control for hinged landing door  | 1.20.94090_Instructions_Vx.x_TSG sinus drive  |
| 07       | TSG V4 with Otis 3-wire communication interface  | 1.20.91805_xx_Instructions_Vx.x_TSG_in_DCSS5_AT120  |
| 08       | reserved   |   |
| 09       | reserved   |   |
| 10       | TSG V4 with CanOpen bus communication interface<br>TSG V4 with ThyssenFx bus communication interface   | 1.20.91555_xx_Instructions_Vx.x_TSG-V4-CanOpen<br>1.20.92620_xx_Instructions_Vx.x_TSG-V4-Thyssen-CAN  |
| 11       | reserved   |   |
| 12       | reserved   |   |
| 13       | TSG V4 with Otis Multidrop communication interface   | 1.20.91806_xx_Instructions_Vx.x_TSG_in_OTIS_Multidrop   |
| 14       | reserved   |   |
| 15       | reserved   |   |
| 16       | TSG V4 with CanOpen bus communication interface and TSG sinus drive control<br>TSG V4 with ThyssenFx bus communication interface and TSG sinus drive control   | 1.20.91555_xx_Instructions_Vx.x_TSG-V4-CanOpen<br>1.20.92620_xx_Instructions_Vx.x_TSG-V4-Thyssen-CAN<br>1.20.94090_xx_Instructions_Vx.x_TSG sinus drive |
| 17       | TSG V4 with CanOpen bus communication interface, TSG sinus drive control and emergency power supply<br>TSG V4 with ThyssenFx bus communication interface, TSG sinus drive control and emergency power supply | 1.20.91555_xx_Instructions_Vx.x_TSG-V4-CanOpen<br>1.20.92620_xx_Instructions_Vx.x_TSG-V4-Thyssen-CAN<br>1.20.94090_xx_Instructions_Vx.x_TSG sinus drive |

| Value hA | Function   | Accompanying documents   |
|----------|--|--|
| 18       | TSG V4 with CanOpen bus communication interface, TSG sinus drive control for hinged landing door<br>TSG V4 with ThyssenFx bus communication interface, TSG sinus drive control for hinged landing door   | 1.20.91555_xx_Instructions_Vx.x_TSG-V4-CanOpen<br>1.20.92620_xx_Instructions_Vx.x_TSG-V4-Thyssen-CAN<br>1.20.94090_xx_Instructions_Vx.x_TSG sinus drive  |
| 19       | TSG V4 with control of the car door locking device (FKTV)  | 1.20.92630_xx_Instructions_Vx.x_TSG-FKTV   |
| 20       | TSG V4 with control of the car door locking device (FKTV) and TSG sinus drive  | 1.20.92630_xx_Instructions_Vx.x_TSG-FKTV<br>1.20.94090_xx_Instructions_Vx.x_TSG sinus drive  |
| 21       | TSG V4 with control of the car door locking device (FKTV) and TSG sinus drive for hinged landing door  | 1.20.92630_xx_Instructions_Vx.x_TSG-FKTV<br>1.20.94090_xx_Instructions_Vx.x_TSG sinus drive  |
| 22       | TSG V4 with CanOpen bus communication interface and control of the car door locking device (FKTV)<br>TSG V4 with ThyssenFx bus communication interface and control of the car door locking device (FKTV)   | 1.20.91555_xx_Instructions_Vx.x_TSG-V4-CanOpen<br>1.20.92620_xx_Instructions_Vx.x_TSG-V4-Thyssen-CAN<br>1.20.92630_xx_Instructions_Vx.x_TSG-FKTV   |
| 23       | TSG V4 with CanOpen bus communication interface and control of the car door locking device (FKTV) and TSG sinus drive<br>TSG V4 with ThyssenFx-Bus communication interface and control of the car door locking device (FKTV) and TSG sinus drive   | 1.20.91555_xx_Instructions_Vx.x_TSG-V4-CanOpen<br>1.20.92620_xx_Instructions_Vx.x_TSG-V4-Thyssen-CAN<br>1.20.92630_xx_Instructions_Vx.x_TSG-FKTV<br>1.20.94090_xx_Instructions_Vx.x_TSG sinus drive        |
| 24       | TSG V4 with CanOpen-Bus communication interface and control of the car door locking device (FKTV) and TSG sinus drive for hinged landing door<br>TSG V4 with ThyssenFx-Bus communication interface and control of the car door locking device (FKTV) and TSG sinus drive for hinged landing door   | 1.20.91555_xx_Instructions_Vx.x_TSG-V4-CanOpen<br>1.20.92620_xx_Instructions_Vx.x_TSG-V4-Thyssen-CAN<br>1.20.92630_xx_Instructions_Vx.x_TSG-FKTV<br>1.20.94090_xx_Instructions_Vx.x_TSG sinus drive        |
| 25       | reserved   |  |
| 26       | reserved   |  |
| 27       | TSG V4 with non-contact synchronisation of power driven landing doors - car door   | 1.20.92670_xx_Instructions_V1.4_TSG Non-Contact Synchronisation  |
| 28       | TSG V4 with non-contact synchronisation of power-driven landing doors - landing door   | 1.20.92670_xx_Instructions_V1.4_TSG Non-Contact Synchronisation  |
| 29       | TSG V4 with Otis 3-wire communication interface with control of the car door locking device (FKTV)<br>TSG V4 with Otis 3-wire communication interface with control of the car door locking device (FKTV) and TSG sinus drive<br>TSG V4 with Otis Multidrop communication interface with control of the car door locking device (FKTV)<br>TSG V4 with Otis Multidrop communication interface with control of the car door locking device (FKTV) and TSG sinus drive | 1.20.91805_xx_Instructions_Vx.x_TSG_in_DCSS5_AT120<br>1.20.91806_xx_Instructions_Vx.x_TSG_in_OTIS_Multidrop<br>1.20.92630_xx_Instructions_Vx.x_TSG-FKTV<br>1.20.94090_xx_Instructions_Vx.x_TSG sinus drive |
| 30       | reserved   |  |
| 31       | reserved   |  |
| 32       | TSG V4 with customised setting   | 1.20.91866   |

Table 31: Mode setting with parameter hA

## 6.7.6 Error codes (E parameters)

| Par.      | Function  | Min | Standard | Max | Unit              | Ready | Reset  |
|-----------|---|-----|----------|-----|-------------------|-------|--|
| <b>E0</b> | Travel not limited                                  | 00  | 00       | 999 | Quantity          | No    | Automatically after 15 s or Power on reset   |
| <b>E1</b> | Travel disabled                                     | 00  | 00       | 999 | Quantity          | No    | Automatically after 15 s or Power on reset   |
| <b>E2</b> | EEPROM error  | 00  | 00       | 999 | Quantity          | No    | Power on reset   |
| <b>E3</b> | Blocked on reversing                                | 00  | 00       | 999 | Quantity          | No    | Automatically after 15 s or Power on reset   |
| <b>E4</b> | Encoder signals not clear or not available          | 00  | 00       | 999 | Quantity          | No    | Automatically after 15 s. Shutdown of the drive after several attempts without change. Power on reset. |
| <b>E5</b> | Current sensor monitoring triggered                 | 00  | 00       | 999 | Quantity          | No    | Automatically after 15 s. Shutdown of the drive after several attempts without change. Power on reset. |
| <b>E6</b> | TSG internal monitoring                             | 00  | 00       | 999 | Quantity          | No    | Automatically after 15 s. Shutdown of the drive after several attempts without change. Power on reset. |
| <b>E7</b> | Blocked after switching back on                     | 00  | 00       | 999 | Quantity          | No    | Automatically after 15 s or Power on reset   |
| <b>E8</b> | Number of restarts                                  | 00  | 00       | 999 | Quantity          | Yes   | –  |
| <b>E9</b> | Monitoring of stop input, end stage, self diagnosis | 00  | 00       | 999 | Quantity          | No    | Automatically after 15 s. Shutdown of the drive after several attempts without change. Power on reset. |
| <b>EA</b> | Overcurrent in standstill                           | 00  | 00       | 999 | Quantity          | No    | Automatically after 15 s or Power on reset   |
| <b>Eb</b> | Voltage error                                       | 00  | 00       | 999 | Quantity          | No    | Automatically after 15 s or Power on reset   |
| <b>EC</b> | Motor not ok  | 00  | 00       | 999 | Quantity          | No    | Automatically after 15 s. Shutdown of the drive after several attempts without change. Power on reset. |
| <b>Ed</b> | Motor detection is faulty                           | 00  | 00       | 999 | Quantity          | No    | Restart directly possible if the motor is detected   |
| <b>EE</b> | Load default settings                               | oF  | oF       | on  | oF: off<br>on: on | –     | –  |
| <b>EF</b> | Delete error counter                                | oF  | oF       | on  | oF: off<br>on: on | –     | –  |
| <b>CC</b> | Ext the current level of the menu.                  |     |          |     |                   |       |  |

Table 32: E parameters

### 6.7.7 Operating state (r parameters)

| Par.      | Function                     | Unit | Note   |
|-----------|------------------------------|------|--|
| <b>r0</b> | Actual speed                 | m/s  | Displays the momentary speed.  |
| <b>r1</b> | Setpoint speed               | m/s  | Displays the specified speed.  |
| <b>r2</b> | Current motor current        | A    | Displays the current motor current.  |
| <b>r3</b> | End stage operating voltage  | VDC  | Displays the current voltage in the end stage.   |
| <b>r4</b> | Mains voltage                | VAC  | Displays the last two digits of the mains voltage. Example: Display 30: mains voltage = 230 VAC. |
| <b>r5</b> | Temperature                  | °C   | Displays the current temperature in the end stage.   |
| <b>r6</b> | Door width (xx0000)          | 10 m | Displays the measured door width in multiples of ten metres.                                     |
| <b>r7</b> | Door width (00xx00)          | dm   | Displays the measured door width in decimetres.  |
| <b>r8</b> | Door width (0000xx)          | mm   | Displays the measured door width in millimetres.   |
| <b>r9</b> | Current door status (xx0000) | 10 m | Displays the current door status in multiples of ten metres.                                     |
| <b>rA</b> | Current door status (00xx00) | dm   | Displays the current door status in decimetres.  |
| <b>rb</b> | Current door status (0000xx) | mm   | Displays the current door status in millimetres.   |
| <b>rC</b> | Operating hours (xx0000)     | h    | Displays the operating hours achieved.   |
| <b>rd</b> | Operating hours (00xx00)     | h    | Displays the operating hours achieved.   |
| <b>rE</b> | Operating hours (0000xx)     | h    | Displays the operating hours achieved.   |
| <b>rF</b> | Friction                     | A    |  |
| <b>CC</b> | Exit the current menu level  |      |  |

Table 33: r parameters

## 6.7.8 User setting of the Au parameters

| Par.      | Function  | Note  | Min | Standard | Max | Factor          | Unit             |
|-----------|---|---|-----|----------|-----|-----------------|------------------|
| <b>A0</b> | Setting of the door unlocked position   | See <i>Application note 1.20.91520 "Door unlocking via the skate"</i> .<br><br>If the door arrives in the closed and locked position and the close door signal then drops away, the setting in parameter <b>A0</b> drops off. The door moves by the distance set in <b>A0</b> and takes up the closed and locked position.<br>00: door stays stopped in the closed and locked position<br>01...04: the door opens by 5 mm<br>05...999: the door opens by the set value in mm  | 00  | 00       | 999 |                 | mm               |
| <b>A1</b> | Reversing brake value   | Active if the "Close door" input signal is removed or is reversed.  | 01  | 15       | 50  | 0.1             | m/s <sup>2</sup> |
| <b>A2</b> | Setting of the buffer time between reaching the door zone and unlocking of the door. Only valid in operation with a door locking device controlled by the TSG V4.   | Setting in 100 ms increments (see <i>manual 1.20.92630 "TSG TKTV documentation"</i> ).  | 0   | 4.0      | 99  | 0.1             | s                |
| <b>A3</b> | Distance of the door opening. Only valid in operation with a door locking device controlled by the TSG V4.  | See <i>Manual 1.20.92630 "TSG TKTV documentation"</i> .   | 0   | 5        | 99  | 1<br>Divisor: 1 | cm               |
| <b>A4</b> | Behaviour of the "closed" limit switch on carrying out the function of parameter <b>A0</b> . Only relevant if the "Setting of the door unlocked position" function is active (see parameter <b>A0</b> ). Only valid in operation with a door locking device controlled by the TSG V4. | See <i>Application note 1.20.91520 "Door unlocking via the skate"</i> .<br><br>00 and all other settings > 02: The "closed" limit switch drops off when the door leaves the closed position.<br>01: the "closed" limit switch is active while the function after <b>A0</b> is being carried out, however, drops off when the door and door unlocked position are located 100 mm away from the door locked position.<br>02: The "closed" limit switch is active while the function after <b>A0</b> is being carried out, as long as the door is within the distance of parameter <b>A0</b> . | 0   | 0        | 99  |                 |                  |
| <b>A6</b> | DMC operation: Gate switch detection distance. If the door drive is within this area, the external sensor is not evaluated any further.   | See <i>Manual 1.20.91530 "TSG in DMC documentation"</i> .   | 0   | 20       | 99  |                 | mm               |
| <b>A7</b> | IrDA operation: Setting of the time delay from the time of interruption of communication from the cabin door drive to the landing door drive, if the landing door is unlocked and open. To be set at the door drive of the landing door. The value is limited to 15 s maximum.        | See <i>Manual 1.20.92670 "TSG Contactless synchronisation documentation"</i> .  | 0   | 1        | 99  |                 | s                |
| <b>A8</b> | Additional mechanical transmission  | See ▶ <i>Mechanical transmission [p. 60]</i> .  | 05  | 1.0      | 8.0 |                 |                  |

| Par.      | Function  | Note  | Min | Standard | Max | Factor | Unit |
|-----------|---|---|-----|----------|-----|--------|------|
| <b>A9</b> | Release of the parameter <b>A8</b>                      | See ▶ <i>Mechanical transmission [p. 60]</i> .                | 00  | 00       | 01  |        |      |
| <b>AA</b> | User-defined parameter sets.                            | Change only after consulting the support of Langer & Laumann. | 00  | 00       | 99  |        |      |
| <b>Ab</b> | Reset IP address in TVis web interface to 172.16.1.150. |   | X   | X        | X   | X      | X    |
| <b>AC</b> | IP0   |   | X   | X        | X   | X      | X    |
| <b>Ad</b> | IP1   |   | X   | X        | X   | X      | X    |
| <b>AE</b> | IP2   |   | X   | X        | X   | X      | X    |
| <b>AF</b> | IP3   |   | X   | X        | X   | X      | X    |
| <b>CC</b> | Ext the current level of the menu.                      |   |     |          |     |        |      |

Table 34: Au parameters

## 6.8 Setting the force limitation

### 6.8.1 Basic principles

The maximum allowable speeds, forces and energy values must be checked and recorded by the skilled person carrying out the work at the closing and shear edges after commissioning or after changing parameters at the door. A closing force measuring device for determining dynamic and static forces can be borrowed from Langer & Laumann.

### 6.8.2 Maximum kinetic energy

According to the relevant standards, the maximum kinetic energy  $W_{kin}$  at the closing and shear edges must not exceed 10 J. To this end, it is necessary to know the actual total weight of the component to be moved (door panels, guard, ...) and to enter them before the measuring (see also ▶ *Manual measuring [p. 41]*).

On exceeding the specified value for the kinetic energy the speed must be lowered so that the limits can be met. The maximum speed to be set is calculated as follows:

$$v = \sqrt{\frac{2 \cdot W_{kin}}{m}} \quad \rightarrow \quad v [m/s] = \sqrt{\frac{2 \cdot 10 \text{ J}}{m [kg]}}$$

Where

- v: maximum allowed speed [m/s]
- $W_{kin}$ : kinetic energy [J]
- m: weight [kg]

### 6.8.3 Maximum static force

According to the relevant standards, the maximum static force F at the closing and shear edges must not exceed 150 N. The parameter **P8** (or **b2** closing direction, **b7** opening direction) sets the values for the maximum static force. By increasing the value in **P8** (or **b2** closing direction, **b7** opening direction), the threshold value for obstacle detection is increased.

## 6.8.4 Obstacle detection in closing direction

If the door is blocked in the closing direction and the obstacle detection is activated, the door remains stopped as long as the "Close door" input signal is still applied. At the same time, the relay for "Door blocked" switches. If the "Close door" input signal is still applied, the door continues moving in the closing direction after 5 s.

If it is rerouted (the "open door" input signal is applied), the door moves open in a controlled way. The relay for "door blocked" is switched off as soon as the "open" position is reached. The position at which the door was blocked is saved in the TSG V4 for the next journey. If the "Close door" input signal is applied again, the door travels with normal speed up to approx. 5 cm in front of the obstacle and continues travelling with slow speed (parameter to be set **h6**). If the obstacle is removed, the door continues moving to approx. 5 cm after the obstacle with normal speed. The function of the speed change at the blocked position must be switched off or on by the parameter **bE**.

If the parameter **b4 = on**, the door is reversed automatically in case of blocking. After reaching the "open" position the door closes again. The reversing distance can be set using the parameter **bd**. If **bd** is larger than 00, the door reverses by at least 5 cm. If **bd = 00**, complete reversing takes place.

If the parameter **b3 = on**, the blocked relay is controlled with only one pulse. The length of the pulse is set with parameter **bA**.

The threshold value for the height of the obstacle detection in the closing direction can be set with the parameter **P8** or **b2** and must be checked at the installed door machine.

## 6.8.5 Obstacle detection in opening direction

If the door is blocked in the opening direction and the obstacle detection is activated, the door remains stopped as long as the "Open door" input signal is still applied. At the same time, the relay for "Door blocked" switches. If the "Open door" input signal is still applied, the door continues moving in the opening direction after 5 s. If it is rerouted (the "Close door" input signal is applied), the door moves in a controlled way, the relay for "Door blocked" is switched off as soon as the "closed" position is reached. If a "Open door" input signal is given again, the door continues moving with normal speed.

The obstacle detection in the opening direction is switched on by default and can be switched off with the parameter **b5 = off**. If the obstacle detection is switched on in the opening direction it is active in the whole travel.

In the first 30 % of the travel of the opening direction the obstacle detection can be switched off by the parameter **b6 = off**.

If the parameter **b9 = on**, the door is reversed automatically in case of blocking. After reaching the "closed" position the door opens again. The reversing distance can be set using the parameter **bd**. If **bd** is larger than 00, the door reverses by at least 5 cm. If **bd = 00**, complete reversing takes place.

If the parameter **b8 = on**, the blocked relay is controlled with only one pulse. The length of the pulse is set with parameter **bA**.

The threshold value for the height of the 150 N detection in the opening direction can be set with the parameter **b7**.

## 6.9 Special functions

### 6.9.1 Holding torque in the end positions

A holding torque can be set in the end positions. The holding door causes the door to be held in the respective end position with a force to be set. A differentiation is made between whether an input signal is applied at the inputs ("Open door" or "Close door") or not.

If the holding torque acts in the end position, a value of approx. 35 N/A can be assumed as a guide value for the static force (parameter setting **cC, cd, cE, cF**) (requirements: no external force action, no mechanical transmission, TSG drive with 24 V nominal voltage).

#### ATTENTION

A holding torque that is too high reduces the life of the motor.

— Only set the holding torque as high as absolutely required.

#### 6.9.1.1 Holding torque without applied input signal

A holding torque can be set so that the door is held in the end position even if an input signal is not applied at the TSG V4. The holding torque in the "open" position without "Open door" signal is set with the parameter **cC**, the holding torque in the "closed" position without "Close door" signal with the parameter **cd**.

**Example** The higher level control system issues the "Close door" input signal, the door moves closed. If the door is closed, the input signal is removed by the control system and the door is de-energised. On travelling through the well, it is now possible for the door to slowly stop due to vibrations or mechanical stress in the system and the safety circuit is opened. The holding torque can be variably set to prevent this.

#### 6.9.1.2 Holding torque with applied input signal

A holding torque can be set so that the door is held in the end position even if an input signal is applied at the TSG V4. The holding torque in the "open" position without "Open door" signal is set with the parameter **cE**, the holding torque in the "closed" position with "Close door" signal with the parameter **cd**.

### 6.9.2 Braking function in case of fast manual movement

If an open signal is applied to the TSG V4 electronics, the door opens. If the open signal is removed while the door is moving without another control signal being applied, provided the door is coupled with a landing door – it can still be driven in the closing direction at high speed due to possibly present landing door closing springs. To avoid excessive closing speeds, in this case the braking function is activated automatically.

The braking function is active if one or both of the parameters **cC** and **cE** is set with a value  $> 1.0$ .

### 6.9.3 Closing the door on deactivation or failure of the external protective device

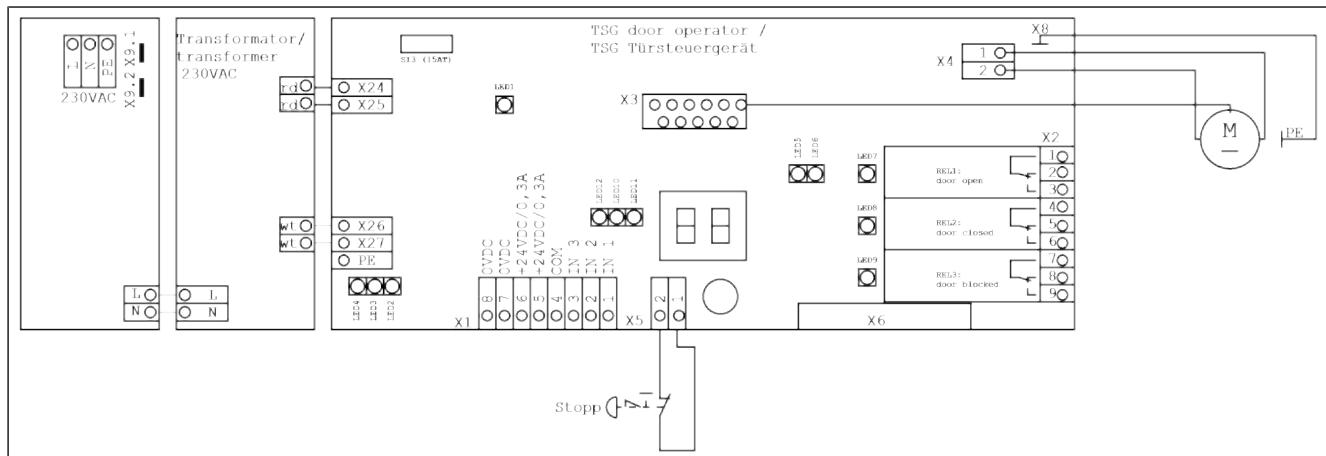
If an external protective device (e.g. Light grid) is deactivated or fails on closing the door, the maximum kinetic energy  $W_{kin}$  at the closing and shear edges must be reduced and must not exceed 4 J.

The jostle function can be used if an external protective device is deactivated or fails on closing the door.

If the parameter **h3 = 03** is set, the jostle function can be executed by simultaneously applying the input signals X1.2 and X1.3. If the "Close signal and the "Jostle" signal are applied at the same time, the door moves with slower speed. On reaching the obstacle the force is switched to a fixed value after a second.

## 6.9.4 Stop function

The following figure shows the required external wiring of terminal block X5.



III. 23: Example stop function wiring

If the connection between terminals 1 and 2 of terminal block X5 is opened, the motor coasts to a stop. "RR" appears in the display.

After restoring the connection the TSG V4 restarts in normal mode.

### 6.9.5 Leading limit switch

The output signals for “Door open” and “Door closed” (terminal block X2) can be set to be leading. In keeping with the configuration, they switch before the teached-in end position has been completely reached. The door drive continues moving the door until the teached-in end position has been completely reached, even if the input signal recedes. Any connected protective device within the set area is disregarded.

The following table shows which leading is achieved with which setting of the parameter **h2**.

| Parameter h2 | Leading        |                  | Parameter h2 | Leading        |                  |
|--------------|----------------|------------------|--------------|----------------|------------------|
|              | Door open [cm] | Door closed [cm] |              | Door open [cm] | Door closed [cm] |
| 00           | 0              | 0                | 16           | 3              | 3                |
| 01           | 0              | 0                | 17           | 5              | 0                |
| 02           | 0              | 1                | 18           | 10             | 0                |
| 03           | 1              | 0                | 19           | 15             | 0                |
| 04           | 1              | 1                | 20           | 0              | 5                |
| 05           | 0              | 2                | 21           | 5              | 5                |
| 06           | 2              | 0                | 22           | 10             | 5                |
| 07           | 1              | 2                | 23           | 15             | 5                |
| 08           | 2              | 1                | 24           | 0              | 10               |
| 09           | 2              | 2                | 25           | 5              | 10               |
| 10           | 0              | 3                | 26           | 10             | 10               |
| 11           | 3              | 0                | 27           | 15             | 10               |
| 12           | 1              | 3                | 28           | 0              | 15               |
| 13           | 3              | 1                | 29           | 5              | 15               |
| 14           | 2              | 3                | 30           | 10             | 15               |
| 15           | 3              | 2                | 31           | 15             | 15               |

## 6.9.6 Mechanical transmission

### 6.9.6.1 Description

This section applies to the TSG V4 software version V4.60.12 and higher

A fixed set gear transmission ratio is stored in the default setting in the TSG V4. However, in several applications, speed increases or reductions are desired. A changed mechanical transmission causes the forces, the speeds and the accelerations to be different to those expected. To level out the difference, the existing mechanical transmission can be adjusted in TSG V4.

### 6.9.6.2 Parameter

To set a changed mechanical transmission, the parameters **A8** and **A9** must be adjusted accordingly.

| Par.      | Function                           | Note | Min | Standard | Max | Factor | Unit |
|-----------|------------------------------------|------|-----|----------|-----|--------|------|
| <b>A8</b> | Additional mechanical transmission |      | 0.5 | 1.0      | 8.0 |        |      |
| <b>A9</b> | Release of the parameter <b>A8</b> |      | 00  | 00       | 01  |        |      |
| <b>CC</b> | Ext the current level of the menu. |      |     |          |     |        |      |

When the parameter **A8** is changed and released by parameter **A9**, all speed, acceleration and braking parameters are automatically changed accordingly.

When the default settings are loaded, parameters **A8** and **A9** are not reset to the defaults.

When the default settings are loaded, all speed, acceleration and braking parameters are changed depending on the set mechanical transmission.

### 6.9.6.3 Example

If the mechanical layout differs from the standard layout, a different mechanical transmission exists.

#### Sequence

1. Commission the system with a measurement process.
2. Determine the transmission to be set.
  - Read off the measured door width from the TSG web interface or in the parameters **r6** to **r8**. **Example:** 5.0 m
  - Measure the existing door width manually (from end stop to end stop, not including the width of the door panel coupler). **Example:** 2.0 m
  - Calculate the transmission: transmission = door width in the TSG / real door width. **Example:** 5.0 m / 2.0 m = 2.5
3. Enter the calculated transition in the parameter **A8**. **Example:** **A8 = 2.5**
4. Activate the changed transmission with the parameter **A9 = 01**.
  - ⇒ The TSG updates the internal travel data based on the new transmission.

## 7 Operation

### 7.1 Restart after power failure and restored mains

After a power failure and mains recovery, the TSG V4 checks the teached-in positions (reference journey). To do so, the TSG V4 moves with reduced speed until both end positions are reached and detected. This speed can be set with the parameter ***h6***.

The travel must be free of obstacles during the reference journey. If this is not the case, the obstacle is detected and is output in the display of the TSG V4 electronic components "E 7" (see also ▶ *Error codes (E parameters) [p. 52]*). The referencing then begins again.

### 7.2 Normal operation

In normal operation the TSG V4 works automatically according to the set parameters.

## 8 Maintenance

### 8.1 Maintenance safety instructions

#### DANGER



#### **Risk of fatal injury from electrical current**

Dangerously high electrical voltages may be present on cables and terminals.

- Only qualified electricians may work on electrical components.
- Before starting work on electrical components, the five electrical safety rules must be observed:
  - Disconnect
  - Secure against reconnection
  - Verify absence of voltage
  - Earth and short-circuit
  - Provide protection against adjacent live parts

#### WARNING



#### **Risk of injury from moving parts**

Error and problem solving (troubleshooting) and maintenance and repair work that is carried out by unauthorised or unqualified personnel can lead to serious accidents due to their lack of relevant technical knowledge and skills. Moving parts can cause injury.

- Wear the prescribed personal protective equipment.
- Allow authorised skilled personnel of Langer & Laumann only to correct errors and solve problems.
- Allow Langer & Laumann only to set, repair or replace safety-related components.
- If you have any questions or problems, contact the customer service of Langer & Laumann.

#### CAUTION



#### **Risk of burning on the motor**

The motor of the TSG V4 can get very hot in continuous operation, thus causing a risk of burns.

- Allow the motor to cool before starting the work.
- Wear the specified personal protective equipment (suitable protective gloves).

## 8.2 Regular checks

The following checks must be carried out at regular intervals, however, at least every three months:

1. Check the doors, the drives and the electronics for identifiable damage and defects.
2. Check the easy movement of the door.
3. Check the timing belt for wear and mechanical tension.
4. Check the function of the facility (safety devices, inputs and outputs).
5. After completing the checks, restart all protective and safety devices.

If damage and/or defects are found, the facility must be taken out of service immediately. All damage and defects must be removed before renewed commissioning.

## 9 Troubleshooting

### 9.1 Troubleshooting safety instructions

#### DANGER



#### **Risk of fatal injury from electrical current**

Dangerously high electrical voltages may be present on cables and terminals.

- Only qualified electricians may work on electrical components.
- Before starting work on electrical components, the five electrical safety rules must be observed:
  - Disconnect
  - Secure against reconnection
  - Verify absence of voltage
  - Earth and short-circuit
  - Provide protection against adjacent live parts

#### WARNING



#### **Risk of injury from moving parts**

Error and problem solving (troubleshooting) and maintenance and repair work that is carried out by unauthorised or unqualified personnel can lead to serious accidents due to their lack of relevant technical knowledge and skills. Moving parts can cause injury.

- Wear the prescribed personal protective equipment.
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- If you have any questions or problems, contact the customer service of Langer & Laumann.

#### CAUTION



#### **Risk of burning on the motor**

The motor of the TSG V4 can get very hot in continuous operation, thus causing a risk of burns.

- Allow the motor to cool before starting the work.
- Wear the specified personal protective equipment (suitable protective gloves).

## 9.2 Error with displayed error code

If the TSG V4 electronic components detect an error, an error code appears on the display (see also ▶ [Error codes \(E parameters\) \[p. 52\]](#)). The following table lists possible causes and troubleshooting actions for each error code.

| Par.      | Function             | Meaning  | Possible cause  | Remedy   |
|-----------|----------------------|--|---|--|
| <b>E0</b> | Travel not limited   | The door is outside the teached-in door distance by at least 5 cm.   | Timing belt tension has changed.  | Tighten the timing belt. Start measuring journey. <sup>1</sup>                     |
|           |                      |  | Travel incorrectly measured.  | Start measuring journey. <sup>1</sup>  |
|           |                      |  | Door mechanics have been changed.   | Check the mechanics. Start measuring journey. <sup>1</sup>                         |
|           |                      |  | No defined end stops available.   | Retrofit end stops on the car. Start measuring journey. <sup>1</sup>               |
| <b>E1</b> | Travel disabled      | <p>The door does not move. This error occurs <u>outside</u> the area of the blocked detection. The blocked detection is set <u>within</u> the area of the blocked detection and "bL" appears in the display.</p> <p>The current door travel is shorter than the door width teached-in during the reference journey. This error resets itself after 15 seconds. During this time, the door drive does not respond to input signals at X1. If input signals exist at X1, the door drive starts with a reference journey with slow speed.</p> | Timing belt tension has changed.  | Tighten the timing belt. Start measuring journey. <sup>1</sup>                     |
|           |                      |  | Landing door limits the travel.   | Uncouple the landing door from the car door. Start measuring journey. <sup>1</sup> |
|           |                      |  | Blocking occurs within the area in which the blocked detection is switched off. | Check the door travel.   |
|           |                      |  | The door is blocked at least three times consecutively during the opening.      | Check the door travel.   |
|           |                      |  | The door is blocked at least ten times consecutively during the closing.        | Check the door travel.   |
|           |                      |  | Door locking device has not unlocked.   | Check the mechanics of the door.   |
|           |                      |  | Door measuring journey was faulty or was not carried out.                       | Start measuring journey. <sup>1</sup>  |
| <b>E2</b> | EEPROM error         | The drive is stopped if an EEPROM error occurs.  | Possible hardware defect.   | TSG V4Replace electronic components.   |
| <b>E3</b> | Blocked on reversing | The door drive has detected an obstacle and reverses. The door was also blocked on reversing.  | There is an obstacle in the door.   | Check the door travel.   |
|           |                      | The door drive reverses due to the triggering of the external sensor. The door was also blocked on reversing.  |   |  |
|           |                      | The door drive has detected an obstacle in the opening direction and reverses. During the reversing the external sensor also triggers.   |   |  |

| Par.      | Function                                   | Meaning  | Possible cause  | Remedy   |
|-----------|--|--|---|--|
| <b>E4</b> | Encoder signals not clear or not available | The encoder (encoder at the motor) does not send any values to the TSG V4. | Display of <b>E4</b> flashes fast and regularly: cable to the encoder is not connected.                     | Connect cable to the encoder.                              |
|           |  |  | Display of <b>E4</b> flashes fast and regularly: cable to the encoder is damaged.                           | Replace the cable to the encoder.                          |
|           |  |  | Display of <b>E4</b> flashes fast and regularly: cable to the motor is not connected.                       | Connect cable to the motor.                                |
|           |  |  | Display of <b>E4</b> flashes fast and regularly: Cable to the motor is damaged.                             | Replace the cable to the motor or the motor.               |
|           |  |  | Display of <b>E4</b> flashes on for 0.5, off for 1.5 seconds: motor connection cores are twisted.           | Test motor protection cores and correct the connection.    |
|           |  |  | Display of <b>E4</b> flashes on for 0.5 seconds, off for 1.5 seconds: encoder connection cores are twisted. | Check the encoder connection cores and correct connection. |
|           |  |  | Display of <b>E4</b> flashes on for 1.0 seconds, off for 1.0 seconds: end stage is defective.               | TSG V4-Replace electronic components.                      |
|           |  |  | Wrong operating voltage.  | Check operating voltage and correct if necessary.          |
| <b>E5</b> | Current sensor monitoring triggered        | The monitoring of the current sensor has triggered.                        | Cable to the motor damaged.   | Replace the cable to the motor or the motor.               |
|           |  |  | Current sensor is defective.  | TSG V4-Replace electronic components.                      |
|           |  |  | Wrong operating voltage.  | Check operating voltage and correct if necessary.          |
|           |  |  | CPU, RAM or ROM is defective.   | TSG V4-Replace electronic components.                      |
| <b>E6</b> | TSG internal monitoring                    | Check CPU, RAM and ROM.  | RAM triggered.  | TSG V4-Replace electronic components.                      |
|           |  |  | Display of <b>E6</b> flashes on for 1.5 seconds, off for 0.5 seconds: run time monitoring has triggered.    |  |
|           |  |  | Display of <b>E6</b> flashes on for 1.0 seconds, off for 1.0 seconds: timing monitoring has triggered.      |  |
|           |  |  | Display of <b>E6</b> flashes on for 0.5 seconds, off for 1.5 seconds: ROM has triggered.                    |  |

| Par.      | Function  | Meaning  | Possible cause  | Remedy  |
|-----------|---|--|---|---|
| <b>E7</b> | Blocked after switching back on                     | Door was blocked after mains restored.   | After the TSG V4 is switched on again or an error has occurred, the door must rerefence itself. If the door is blocked during this travel the error is triggered. The door mechanics have been changed, but the TSG V4 has not been teached-in again. | Check the mechanics. Start measuring journey. <sup>1</sup>                  |
| <b>E8</b> | Number of restarts                                  | Counter for the number of mains starts.  | Mains power has failed, the TSG V4 electronic components carry out a restart.   | Check supply cable.   |
|           |   |  |   | Check backup fuse.  |
|           |   |  |   | Check fuse on the TSG V4 electronic components electronic components.       |
|           |   |  |   | If necessary, replace TSG V4 electronic components.                         |
| <b>E9</b> | Monitoring of stop input, end stage, self diagnosis |  | End stage is defective.   | TSG V4-Replace electronic components.                                       |
|           |   |  | Set parameter is incorrect.   | Check parameter and change if necessary.                                    |
| <b>EA</b> | Overcurrent in standstill                           | The connected motor draws too much current.  | End stage is defective.   | TSG V4-Replace electronic components.                                       |
|           |   |  | Current sensor is defective.  | TSG V4-Replace electronic components.                                       |
| <b>Eb</b> | Voltage error                                       | The various operating voltages on the TSG V4 electronic components are monitored and evaluated. An error has occurred. | 5 V not ok.   | TSG V4-Replace electronic components.                                       |
|           |   |  | <b>Eb</b> display flashes on for 0.5 seconds, off for 1.5 seconds:<br>12 V not ok.  |   |
|           |   |  | <b>Eb</b> display flashes on for 1.0 seconds, off for 1.0 seconds:<br>24 V not ok.  |   |
|           |   |  | <b>Eb</b> display flashes on for 1.5 seconds, off for 0.5 seconds:<br>38 V not ok.  |   |
| <b>EC</b> | Motor is faulty                                     | The connected motor is damaged.  | An incorrect motor is connected.  | Replace the motor.  |
|           |   |  | Cable to the motor damaged.   | Replace the cable to the motor or the motor.                                |
|           |   |  | Operating voltage too low.  | Check the operating voltage and correct if necessary.                       |
| <b>Ed</b> | Motor detection is faulty                           |  | The motor is not detected by the cable to the encoder.  | Test the cable to the encoder and start the measuring journey. <sup>1</sup> |
|           |   |  | Short circuit in encoder connector.   | Test the encoder connector and start measuring journey. <sup>1</sup>        |

| Par.      | Function   | Meaning  | Possible cause  | Remedy   |  |
|-----------|--|--|---|--|--|
| <b>EH</b> | Temporary warning message:<br>Motor is faulty.<br>The <b>EH</b> display is only shown as long as the error is queued. No error counter is stored, a readout is not possible.                   | The internal resistance of the motor is higher than expected.                          | The connected motor is damaged.                                       | Replace the motor.   |  |
|           |  |  | The cable to the motor is too long.                                   | Check the wiring. If it has been lengthened, change it back.       |  |
|           |  |  | Operating voltage too low.  | Check operating voltage and correct if necessary.                  |  |
| <b>EL</b> | Temporary warning message:<br>Motor is faulty.<br>The <b>EL</b> display is only shown as long as the error is queued. No error counter is stored, a readout is not possible.                   |  | Cable to the motor damaged.   | Replace the cable to the motor or the motor.                       |  |
|           |  |  | Cable to the encoder is damaged.                                      | Replace the cable to the encoder.                                  |  |
|           |  |  | Operating voltage too low.  | Check operating voltage and correct if necessary.                  |  |
| <b>En</b> | CAN bus communication is interrupted or disturbed.<br>The <b>En</b> display is only shown as long as the error is queued. No error counter is stored, a readout is not possible.               | The CAN bus connected to the additional circuit board is interrupted or faulty.        |   | Check CAN bus cable and connections.                               |  |
|           |  |  |   | Check CAN bus master.  |  |
| <b>Eu</b> | Additional communication circuit board is interrupted or faulty.<br>The <b>Eu</b> display is only shown as long as the error is queued. No error counter is stored, a readout is not possible. | Communication with the connected additional circuit board is interrupted or disrupted. | Flat ribbon cable not plugged in correctly or is defective.           | Plug in flat ribbon cable or replace TSG V4 electronic components. |  |
|           |  |  | Wrong additional circuit board selected via the parameter <b>hA</b> . | Correct value in parameter <b>hA</b> .                             |  |
|           |  |  | Additional circuit board is defective.                                | TSG V4-Replace electronic components.                              |  |
| <b>EE</b> | Load default settings  |  |   |  |  |
| <b>EF</b> | Delete error counter   |  |   |  |  |

1. See also ▶ *Manual measuring [p. 41]*.

Table 35: Meaning of the error codes for troubleshooting

### 9.3 Error without displayed error code

The following table contains information on errors for which an error code cannot be displayed when they occur.

| Error                 | Possible cause          | Remedy  |
|-----------------------|-------------------------|---|
| Drive is not running. | TSG V4 is de-energised. | Switch on mains power. Check LED 1, LED 2, LED 3 and LED 4. |

Table 36: Further possible causes of error

## 10 Dismantling and disposal

### 10.1 Dismantling and disposal safety instructions

#### DANGER



#### Risk of fatal injury from electrical current

Dangerously high electrical voltages may be present on cables and terminals.

- Only qualified electricians may work on electrical components.
- Before starting work on electrical components, the five electrical safety rules must be observed:
  - Disconnect
  - Secure against reconnection
  - Verify absence of voltage
  - Earth and short-circuit
  - Provide protection against adjacent live parts

#### CAUTION



#### Risk of burning on the motor

The motor of the TSG V4 can get very hot in continuous operation, thus causing a risk of burns.

- Allow the motor to cool before starting the work.
- Wear the specified personal protective equipment (suitable protective gloves).

#### ATTENTION

#### Risk of environmental damage

Handling and disposal of hazard substances such as lubricants and cleaning agents are subject to legal provisions. If operating supplies and lubricants are not disposed of properly, the environment can be damaged.

- Make sure that the operating supplies are disposed of properly.
- Do not mix waste oil that is produced with other substances or liquids.
- If you have any questions, contact the customer service of Langer & Lau-mann.

## 10.2 Disposal

If a return or disposal agreement has not been concluded, recycle or reuse the dismantled parts:

1. Scrap metals.
2. Recycle plastic element.
3. Dispose of the other components according to their material properties.

If you have any questions, contact the customer service of Langer & Laumann.

**Electronic components** The following electronic components must be disposed of separately:

- Displays, display devices
- Electrical supply
- Controls
- Circuit boards with electronic components

**Used operating materials** Detailed information on disposal of the lubricants used can be found in the safety data sheets of the lubricants and cleaning agents.

## 11 Declaration of incorporation

The original EC declaration of Incorporation for the TSG V4 is available on the internet: [www.lul-ing.de](http://www.lul-ing.de)



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